

# Multifunction Counter/Tachometer H7CX-□-N

# **Ultra-compact Counter Provides More Complete Functionality.**

#### **Basic Features**

- Short body with depth of only 59 mm (for 12 to 24-VDC Models with Screw Terminals).\*1
- Better readability with character height of 12 mm on 4-digit models and 10 mm on 6-digit models.
- The present value display characters can be switched between red, green, and orange.\*2

#### Safety and Reliability

• New set value limit and counter functions have been added.

#### Other Features

- Front Panel can be changed to white or light gray.\*3
- Models with two independent tachometer inputs have been added to the series.
- \*1.For 100 to 240-VAC Models with Screw Terminals: 78 mm, Models with Sockets: 63.7 mm (case dimension). \*2.The H7CX-A11 and H7CX-R11 have only red characters.
- \*3. The Front Panel can be replaced with an optional Front Panel (except for Tachometer-only Models).



**NEW** 

Refer to Safety Precautions on page 52.

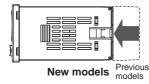
#### **Features**

# Basic Features Ultra Short Body

The body depth has been greatly reduced. Helps in making thinner control panels.

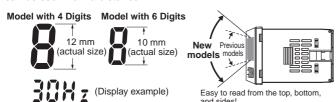
12 to 24-VDC Models with Screw Terminals: 59 mm 100 to 240-VAC Models with Screw Terminals: 78 mm\* Models with Sockets: 63.7 mm (case dimension)

\* Power supply circuit and input circuits are isolated for safety and reliability.



#### **Easier to Read**

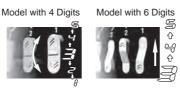
For better readability, the character height for the present value display is 12 mm on models with 4 digits, the largest class in the industry. The wide viewing angle and brightness provide excellent visibility. The number of display segments has also been increased to make settings easier to understand, and the present value display can be switched between red, green, and orange so that output status can be seen from a distance.



Note: The display color can be switched on all models except for the H7CX-A11 and H7CX-R11.

#### The Easiest Operation

Operation is simplified by the Up/Down Key for each digit on 4-digit models and Up Key for each digit on 6-digit models.



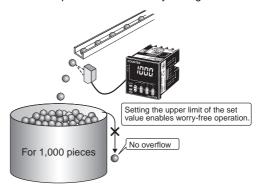
# Safety and Reliability Isolated Power Supply and Input Circuits

Power supply circuit and input circuits are isolated inside the Counter/ Tachometer. Previous non-isolated counters had wiring restrictions and could be damaged if wired incorrectly. The H7CX removes these worries.

Note: Except 12 to 24-VDC models.

#### **Set Value Limit**

You can set an upper limit for the set value to prevent unexpected operation of output devices caused by setting mistakes.



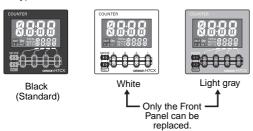
#### **Output Counter**

The output counter counts the number of times the output turns ON (alarms can be displayed and the count can be monitored in increments of 1,000 operations). This counter is useful in managing the service life of the Counter/Tachometer or the load.

#### Other Features

# The front color can be changed simply by replacing the Front Panel.

The Front Panel can be replaced with an optional Front Panel (sold separately) with a different color to match the installation site. Select from black, white, and light gray (except for models with tachometer function only).



#### **Universal NPN/PNP Input**

DC 2-wire sensors can be connected for a wide range of input devices.

# Waterproof, Dust-proof Structure (UL508 Type 4X and IP66)

Worry-free application is possible in locations subject to water. **Note:** When the Y92S-29 Waterproof Packing is used.

#### **Key Protection**

Select from any of seven protection patterns. Use the best one for the application.

#### **New Functions**

Many useful functions have been added, including a Twin Counter Mode and many tachometer functions to handle even more applications.

**New Tachometer Functions** 

- Control with two independent inputs (independent measurements, differential, absolute ratio, and error ratio)
- Peak/bottom hold function
- · Output hysteresis setting
- · Output OFF delay
- Switching the measurement method (pulse cycle/pulse width)
- Startup time
- · Auto-zero time
- · Averaging method/Number of averaging times
- · AMD-compatible Mode

## **Model Number Structure**

# **Model Configuration**

H7CX Series								
							1	
		H7C	X-A-seri	es Multifunction	Preset Counter	H7CX-R-series	H7CX-R-series Digital Tachometer	
Model								
Classifica	tion		Preset co	unter	Preset counter/tachometer	Tachometer		
Model		H7CX-A	□-N	H7CX-A4W□-N	H7CX-AW□-N/-AU□-N	H7CX-R11□-N	H7CX-R11W□-N	
	1-stage preset counter	Yes		Yes	Yes		No	
	2-stage preset counter	No		Yes	Yes	No		
Function	Total and preset counter	Yes		Yes	Yes	No		
	Batch counter	No		Yes	Yes	No		
	Dual counter	No		Yes	Yes	No		
	Twin counter	No		Yes	Yes	No		
	Tachometer	No		No	Yes*1		Yes	
Tachometer input		No		No	Yes 1 input or 2 inputs (independent measurements, differential, absolute ratio value, and error ratio value)	Yes 1 input	Yes 2 inputs (independent measurement) only	
Settings		1-stag	е	2-stage		1-stage		
External connections		11-pin socket		Screw te	rminals	11-pin socket		
Display co	olor of present value	Red		Red, green,	or orange	Red		
Display digits		4 or 6 di	gits 4 digits		6 digits	6 digits		

<sup>\*1.</sup> Set the tachometer input mode from the function setting mode to switch to the tachometer function.

#### **Model Number Legend** (Not all possible combinations of functions are available.)

#### 1. Type

Symbol	Meaning
Α	Standard type
R	Tachometer

#### 4. Settings

Symbol		Meaning	
	None	1-stage setting	
	U	Factory-set to 1-stage setting	
	W	Factory-set to 2-stage setting*	

<sup>\*</sup> The H7CX-R11W□ is a 1-stage (2 inputs and outputs) rather than a 2-stage Counter.

#### 2. External connections

	Symbol	Meaning			
	None	Screw terminals			
	11	11-pin socket			

#### 5. Output type

	Symbol	Meaning
	None	Contact output or contact output + transistor output
•	S	Transistor output

#### 3. Digits

Symbol	Meaning
None	6 digits
4	4 digits

#### 6. Supply voltage

Symbol	Meaning
None	100 to 240 VAC at 50/60 Hz
D	12 to 24 VDC
D1	12 to 24 VDC/24 VAC at 50/60 Hz

# **Ordering Information**

### **List of Models**

Туре	Classification	Configuration	External connections	Settings	Display digits	Outputs	Power supply voltage	Model
					4 digits	Contact output (SPDT)	- 100 to 240 VAC	H7CX-A114-N
						Transistor output (SPST)		H7CX-A114S-N
						Contact output (SPDT)	12 to 24 VDC/24 VAC	H7CX-A114D1-N
			11-pin socket			Contact output (SPDT)	100 to 240 VAC	H7CX-A11-N
					6 digits	Transistor output (SPST)	100 to 240 VAC	H7CX-A11S-N
					o digits	Contact output (SPDT)	12 to 24 VDC/24 VAC	H7CX-A11D1-N
		1-stage preset				Transistor output (SPST)	12 to 24 VDC/24 VAC	H7CX-A11SD1-N
		<ul><li>counter</li><li>Total and preset</li></ul>		1-stage		Contact output (SPDT)	100 to 240 VAC	H7CX-A4-N
		counter			4 diaita	Transistor output (SPST)	100 to 240 VAC	H7CX-A4S-N
					4 digits	Contact output (SPDT)	42 to 24 \/DC	H7CX-A4D-N
	Preset counter					Transistor output (SPST)	12 to 24 VDC	H7CX-A4SD-N
						Contact output (SPDT)	400 to 240 \/AC	H7CX-A-N
		1-stage preset counter     2-stage preset counter     Total and preset counter     Batch counter     Dual counter     Twin counter			6 digits	Transistor output (SPST)	100 to 240 VAC	H7CX-AS-N
						Contact output (SPDT)	12 to 24 VDC	H7CX-AD-N
1170V A						Transistor output (SPST)		H7CX-ASD-N
H7CX-A Series			Screw terminals		4 digits	Contact output (SPST + SPDT)	100 to 240 VAC	H7CX-A4W-N
				4 digits	Transistor output (DPST)	12 to 24 VDC	H7CX-A4WSD-N	
				2-stage		Contact output (SPST + SPDT)	100 to 240 VAC	H7CX-AW-N
						Transistor output (DPST)		H7CX-AWS-N
		<ul> <li>1-stage preset counter</li> </ul>		_		Contact output (SPST + SPDT)	40.4- 04.1/20/04.1/4.0	H7CX-AWD1-N
					 	T (DDOT)	12 to 24 VDC/24 VAC	H7CX-AWSD1-N
	Preset counter/				6 digits	Transistor output (DPST) 12 to 24 VDC	12 to 24 VDC	H7CX-AWSD-N
	Tachometer					Contact output (SPDT) + Transistor output (SPST)	100 to 240 VAC	H7CX-AU-N
						Contact output (SPDT) + Transistor output (SPST)	12 to 24 VDC/24 VAC	H7CX-AUD1-N
						Transistor output (DPST)		H7CX-AUSD1-N
				1-stage (1 input and		Contact output (SPDT)	100 to 240 VAC	H7CX-R11-N
H7CX-R	Took ow - t	. Took ow - t	44 min ===!: 1	output)	6 digits	Contact output (SPD1)	12 to 24 VDC/24 VAC	H7CX-R11D1-N
Series	Tachometer	Tachometer	11-pin socket			Contact output (SPDT + SPST)	100 to 240 VAC	H7CX-R11W-N
							12 to 24 VDC/24 VAC	H7CX-R11WD1-N

Note: 1. The functions that are provided depend on the model. Check detailed specifications before ordering.

2. Refer to page page 37 and later for information on H7CX-R Tachometers.

# **Accessories (Order Separately)**

# Front Panels (Replacement Part)

Model	Color	Applicable Counters	Page
Y92P-CXC4G	Light gray (5Y7/1)	4-digit Counter	
Y92P-CXC4S	White (5Y9.2/0.5)		
Y92P-CXC4B	Black (N1.5)		12
Y92P-CXC6G	Light gray (5Y7/1)	6-digit Counter	12
Y92P-CXC6S	White (5Y9.2/0.5)		
Y92P-CXC6B	Black (N1.5)		

Note: 1. You can change the color of the Front Panel when mounting the Counter. The Counter is shipped with a black (N1.5) Front Panel.

2. "COUNTER" is printed on the front of Replacement Front Panels.

#### **Soft Cover**

Model	Remarks	Page	
Y92A-48F1		12	

#### **Hard Cover**

Model	Remarks	Page	
Y92A-48		12	

#### Flush Mounting Adapter

Model Remarks		Page
Y92F-30 Included with models with screw terminals.		
Y92F-45	Use this Adapter to install the Counter/ Tachometer in a cutout previously made for a DIN 72 × 72 mm device (panel cutout: 68 × 68 mm).	12

#### **Waterproof Packing**

Model	Remarks	Page
Y92S-29	Included with models with screw terminals.	12

#### **Connection Sockets**

Model	Classification	Connectable Counter/ Tachometers	Remarks	Page
P2CF-11	Front-connecting Socket			
P2CF-11-E	Front-connecting Socket (Finger-safe Type)	H7CX-□11□-N	Round crimp terminals cannot be used on Finger-safe Sockets. Use forked crimp terminals.	13
P3GA-11	Back-connecting Sockets		A Y92A-48G Terminal Cover can be used with the Socket to create a finger-safe construction.	

#### **Terminal Covers for P3GA-11 Back-connecting Socket**

Model	Remarks	Page
Y92A-48G		13

#### H7CX-A□-N Multifunction Preset Counter

- Easy to check the output status from a long distance with changing display colors<sup>\*1</sup> (red, green, and orange).
- Includes total and preset counter, batch counter, dual counter, twin counter, and tachometer.\*2
- \*1. Not supported by the H7CX-A11□-N.
- \*2. The functions that can be selected depend on the model.



# **Specifications**

### **Ratings**

Item	Models	H7CX-A114□-N	H7CX-A11□-N	H7CX-A4□-N	H7CX-A□-N	H7CX-A4W□-N	H7CX-AW□-N/-AU□-N
Classification Preset counter							Preset counter/ tachometer
Configuration  1-stage preset counter, 1-stage preset counter with total counter (selectable)*1			1-stage/2-stage preset counter, total and preset counter*1, batch counter, dual counter, and twin counter (selectable)	1-stage/2-stage preset counter, total and preset counter*1, batch counter, dual counter, twin counter, and tachometer (selectable)			
	Power supply voltage*2	• 100 to 240 VAC, 50/60 Hz • 24 VAC, 50/60 Hz or 12 to 24 VDC		• 100 to 240 VAC, 50/60 Hz • 12 to 24 VDC			100 to 240 VAC at 50/60 Hz     24 VAC at 50/60 Hz or 12 to 24 VDC     12 to 24 VDC
Ratings	Operating voltage fluctuation range	85% to 110% of rated sup	oply voltage (12 to 24 VDC	: 90% to 110%)			
	Power con- sumption	Approx. 9.4 VA at 100 to	240 VAC, Approx. 7.2 VA/-	4.7 W at 24 VAC/12 to 24 \	/DC, Approx. 3.7 W at 12 to	o 24 VDC	
Mounting	method	Flush mounting or surface	e mounting	Flush mounting			
External c	onnections	11-pin socket		Screw terminals			
Degree of	protection	IEC IP66, UL508 Type 42	(indoors) for panel surfac	e only and only when Y925	S-29 Waterproof Packing is	used.	
Input sign	•	CP1, CP2, reset, and total			. 3	CP1, CP2, reset 1, and re	eset 2
	Maximum counting speed	30 Hz or 5 kHz (switchab *Common setting for CP1					
	Input mode	Increment, decrement, in	crement/decrement (UP/D0	OWN A (command input), l	JP/DOWN B (individual inp	outs), or UP/DOWN C (quad	drature inputs))
Counter	Output mode	N, F, C, R, K-1, P, Q, A, I	K-2, D, and L.			N, F, C, R, K-1, P, Q, A,	K-2, D, L, and H.
	One-shot out- put time	0.01 to 99.99 s					
	Reset system	External (minimum reset signal width: 1 ms or 20 ms, selectable), manual, and automatic reset (internal according to C, R, P, and Q mode operation)				mode operation)	
Tachomet	er	Refer to the separate tab	Refer to the separate table for tachometer function ratings.				
Prescaling	g function	Yes (0.001 to 9.999)	Yes (0.001 to 99.999)	Yes (0.001 to 9.999)	Yes (0.001 to 99.999)	Yes (0.001 to 9.999)	Yes (0.001 to 99.999)
-		Yes (rightmost 3 digits)					
Sensor wa	aiting time	290 ms max. (Control out	put is turned OFF and no i	nput is accepted during ser	nsor waiting time.)		
Input meti	hod	ON residual voltage: 3 V OFF impedance: 100 kΩ Voltage input: High (logic) level: 4.5 to 3	min. 30 VDC DC (Input resistance: appr	·			
External p	ower supply	12 VDC (±10%), 100 mA	(except for H7CX-A□D mo	odels) Refer to Precautions	for Correct Use on page p	age 53 for details.	
Control ou	utput					C (failure level: P, reference /), Leakage current: 0.1 m/	
Display*4		7-segment, negative transmissive LCD Character height Count value: 12 mm (red) Set value: 6 mm (green)	7-segment, negative transmissive LCD Character height Count value: 10 mm (red) Set value: 6 mm (green)	7-segment, negative transmissive LCD Character height Count value: 12 mm (red, green, or orange selectable) Set value: 6 mm (green)	7-segment, negative transmissive LCD Character height Count value: 10 mm (red, green, or orange selectable) Set value: 6 mm (green)	7-segment, negative transmissive LCD Character height Count value: 12 mm (red, green, or orange selectable) Set value: 6 mm (green)	7-segment, negative transmissive LCD Character height Count value: 10 mm (red, green, or orange selectable) Set value: 6 mm (green
Digits		4 digits -999 to 9999 (-3 digits to +4 digits)	6 digits -99999 to 999999 (-5 digits to +6 digits)	4 digits -999 to 9999 (-3 digits to +4 digits)	6 digits -99999 to 999999 (-5 digits to +6 digits)	4 digits -999 to 9999 (-3 digits to +4 digits)	6 digits -99999 to 999999 (-5 digits to +6 digits), tachometer: 0 to 999999
Memory b	ackup	EEPROM (overwrites: 10	0,000 times min.) that can	store data for 10 years mir	i.		*
Operating range	temperature	-10 to 55°C (-10 to 50°C if Counter/Tachometers are mounted side by side) (with no icing or condensation)					
Storage te	emperature range	-25 to 70°C (with no icing or condensation)					
Operating	humidity range	25% to 85%					
Case colo			ont Panels are available to	change the Front Panel co	olor to light gray or white.)		
Attachmer	richments Flush mounting adapter, waterproof packing, terminal cover terminal cover		Flush mounting adapter waterproof packing, terminal cover, label for DIP switch settings				

<sup>\*1. 1-</sup>stage preset counter and total counter functionality.

<sup>\*2.</sup> Do not use the output from an inverter as the power supply. The ripple must be 20% maximum for DC power.

<sup>\*3.</sup> A response of 10 kHz is possible if the response speed is 5 kHz and the 1-stage preset counter input mode is increment, decrement, or increment/ decrement (command input).

<sup>\*4.</sup> The display is lit only when the power is ON. Nothing is displayed when power is OFF.

#### **Tachometer Function Ratings**

Model	H7CX-A114□-N H7CX-A11□-N H7CX-A4□-N H7CX-A□-N H7CX-A4W□-N	H7CX-AW□-N/-AU□-N			
Input mode		Selectable from independent measurements for 1 or 2 inputs, differential input for 2 inputs, absolute ratio for 2 inputs, and error ratio for 2 inputs.			
Pulse measurement method		Periodic measurement		Pulse width measure	ement
Maximum counting speed		30 Hz	1-input mode: 10 kHz Other modes: 5 kHz	30 Hz	1-input mode: 10 kHz Other modes: 5 kHz
Minimum input signal width				30 ms*1	1-input mode: 0.2 ms Other modes: 0.4 ms*
Measuring ranges		0.01 to 30.00 Hz	1-input mode: 0.01 to 10 kHz, Other modes: 0.01 to 5 kHz	0.030 to 999999 s	1-input mode: 0.0002 to 99999 s Other modes: 0.0004 to 99999 s
Sampling period	No tachometer functionality	200 ms min. or continuous selectable (minimum interval of 10 ms)  Continuous (minimum interval of 10 ms)			m interval of 10 ms)
Measuring accuracy		±0.1% FS ±1 digit max. (at	23 ±5°C)		
Output mode		Input mode: Not 2-input independent measurement: HI-LO, AREA, HI-HI, LO-LO 2-input independent measurement: HI-HI, LO-LO			
Auto-zero time		0.1 to 999.9s			
Startup time	]	0.0 to 99.9s			
Averaging		Simple averaging/moving averaging selectable, Processing: OFF, 2, 4, 8, or 16 times			
Hold input		Minimum input signal width	: 20 ms		

<sup>\*</sup> An input OFF time of at least 20 ms is required.

#### **Characteristics**

Insulation resistance		$100~\text{M}\Omega$ min. (at 500 VDC) between current-carrying terminals and exposed non-current-carrying metal parts, and between non-continuous contacts
Dielectric strength		2,000 VAC, 50/60 Hz for 1 min between current-carrying metal parts and non-current-carrying metal parts 2,000 VAC, 50/60 Hz for 1 min between power supply and input circuit for all models except H7CX-□D□ (1,000 VAC for 24 VAC/12 to 24 VDC) 1,000 VAC (for H7CX-□SD□), 50/60 Hz for 1 min between control output, power supply, and input circuit (2,000 VAC for models other than H7CX-□SD□) 1,000 VAC, 50/60 Hz for 1 min between non-continuous contacts
Impulse with	nstand voltage	3.0 kV between power terminals (1.0 kV for models with 24 VAC/12 to 24 VDC or 12 to 24 VDC) 4.5 kV between current-carrying terminals and exposed non-current-carrying metal parts (1.5 kV for models with 24 VAC/12 to 24 VDC or 12 to 24 VDC)
Noise immu	nity	±1.5 kV between power terminals (±480 V for models with 12 to 24 VDC) ±600 V between input terminals Square-wave noise by noise simulator (pulse width: 100 ns/1 μs, 1-ns rise)
Static immu	nity	Malfunction: 8 kV Destruction: 15 kV
Vibration	Destruction	10 to 55 Hz with 0.75-mm single amplitude each in three directions for 2 h each
resistance	Malfunction	10 to 55 Hz with 0.35-mm single amplitude each in three directions for 10 min each
Shock re-	Destruction	300 m/s <sup>2</sup> each in three directions
sistance	Malfunction	100 m/s <sup>2</sup> each in three directions
Life expecta	ncy	Mechanical: 10,000,000 operations min. Electrical: 100,000 operations min. (3 A at 250 VAC, resistive load, ambient temperature condition: 23°C)*
Weight		Approx. 130 g (Counter only)

<sup>\*</sup> Refer to the Life-test Curve.

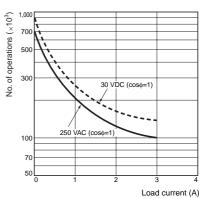
### **Applicable Standards**

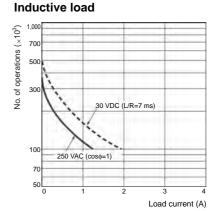
Approved safety standards	cULus (or cURus): UL508/CSA C22.2 No. 14* EN 61010-1 (IEC 61010-1): Pollution degree 2/overvoltage category II B300 PILOT DUTY 1/4 HP 120 VAC, 1/3 HP, 240 VAC, 3 A resistive load VDE0106/P100 (finger protection)			
	(EMI) Emission Enclosure:	EN61326 EN 55011 Grou	p 1 class A	
	Emission AC mains:	EN 55011 Grou		
	(EMS)	EN61326	'	
	Immunity ESD:	EN 61000-4-2:	4 kV contact discharge;	
			8 kV air discharge	
	Immunity RF-interference:	EN 61000-4-3:		
EMC			GHz);	
			10 V/m (Pulse-modulated, 900 MHz ±5 MHz)	
	Immunity Conducted Disturbance			
	Immunity Burst:	EN 61000-4-4:		
			1 kV I/O signal-line	
	Immunity Surge:	EN 61000-4-5:	1 kV line to lines (power and output lines);	
			2 kV line to ground (power and output lines)	
	Immunity Voltage Dip/Interruption: EN 61000-4-11: 0.5 cycle, 100% (rated voltage)			

<sup>\*</sup> The following safety standards apply to models with sockets (H7CX-A11 or H7CX-A114). cUL (Listing): Applicable when an OMRON P2CF(-E) Socket is used. cUR (Recognition): Applicable when any other socket is used.

### Life-test Curve (Reference Values)

#### **Resistive load**





A current of 0.15 A max. can be switched at 125 VDC (cosφ=1) and current of 0.1 A max. can be switched if L/R=7 ms. In both cases, a life of 100,000 operations can be expected.

#### **I/O Functions**

#### Using as a Counter\*1

	CP1, CP2	<ul> <li>(1) In general (except for Dual Counter Mode)</li> <li>Reads counting signals.</li> <li>Increment, decrement, command, individual, and quadrature inputs accepted.</li> <li>(2) When used as a dual counter or twin counter</li> <li>Reads CP1 count signals with CP1 input and CP2 count signals with CP2 input.</li> <li>Increment signals can be input.</li> </ul>
Inputs	Reset/reset 1	(1) In general (except for Dual Counter Mode)  Resets present value and outputs (OUT2 when using the batch counter)*2.  Counting cannot be performed during reset/reset 1 input.  Reset indicator is lit while reset input is ON.  When used as a dual counter or twin counter.  Resets the CP1 present value (to 0).  Counting for CP1 input cannot be performed while the reset 1 input is ON.  The reset indicator is lit while the reset 1 input is ON.
	Total reset or reset 2	The reset function depends on the selected configuration*3.
Outputs	OUT1, OUT2	Outputs signals according to the specified output mode when a set value is reached.

<sup>\*3.</sup> Reset operates as described in the following table. (The reset indicator will not be lit.)

Configuration	Reset operation
1-stage/2-stage preset counter	Does not operate (not used).
Total and preset counter	Resets the total count value. The total count value is held at 0 while the total reset input is ON.
Batch counter	Resets the batch count value and batch output (OUT1). The batch count value is held at 0 while the reset 2 input is ON.
Dual counter	Resets the CP2 present value. Counting for CP2 input cannot be performed while the reset 2 input is ON.
Twin counter	Resets the CP2 present value.

• The following table shows the delay from when the reset signal is input until the output is turned OFF. (Reference values)

Minimum reset signal width	Output delay time
1 ms	0.8 to 1.2 ms
20 ms	15 to 25 ms

#### **Operating Procedures (Tachometer Function)**

	CP1, CP2	Reads counting signals. (The CP2 input can be used when the input mode is not 1-input mode.)
Inputs	Reset/reset 1	<ul> <li>Holds the measurement value and outputs. (The reset 2 input can be used when the input mode is 2-input independent measurement.)</li> <li>The reset indicator is lit when the value is being held.</li> </ul>
Outputs	OUT1, OUT2	Outputs signals according to the specified output mode when a set value is reached.

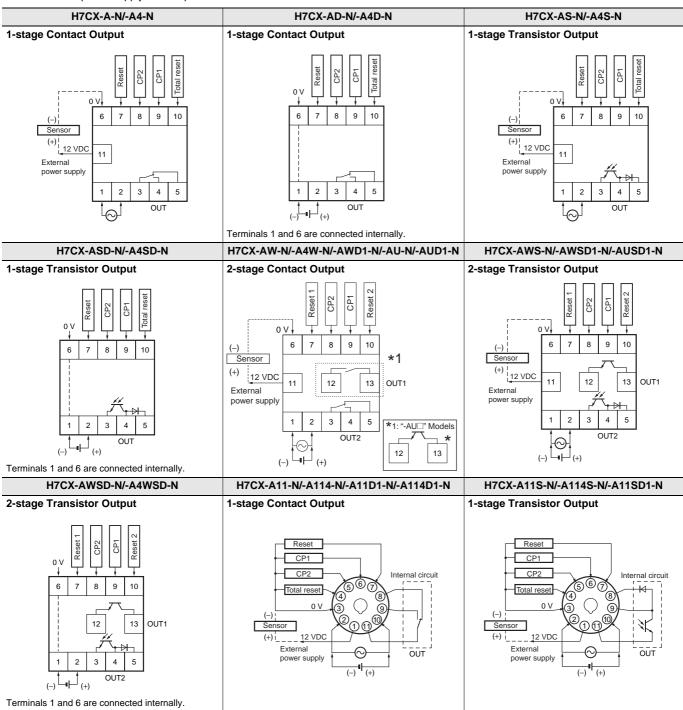
<sup>\*1.</sup> For information on operation of I/O functions, refer to pages page 22 to page 25.
\*2. In increment mode or increment/decrement mode, the present value returns to 0; in decrement mode, the present value returns to the set value with 1-stage models, and returns to set value 2 with 2-stage models.

#### H7CX-A□-N

### **Connections**

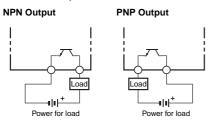
### **Terminal Arrangement**

Confirm that the power supply meets specifications before use.

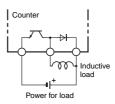


#### **Transistor Output**

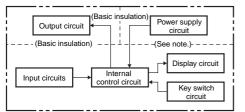
 The transistor output of the H7CX is isolated from the internal circuitry by a photocoupler, so the transistor output can be used as both NPN and PNP output.



 The diode connected to the collector of the output transistor is used to absorb inverted voltage that is generated when an inductive load is connected to the H7CX.



### **Block Diagram**

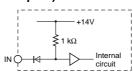


Note: All models except for H7CX-□D-N have basic insulation.

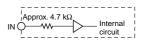
### **Input Circuits**

CP1, CP2, Reset/Reset 1, and Total Reset/Reset 2 Input

#### **No-voltage Inputs** (NPN Inputs)



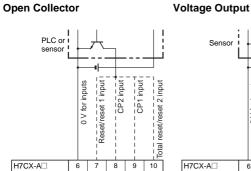
**Voltage Inputs (PNP Inputs)** 

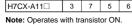


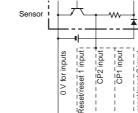
### **Input Connections**

The inputs of the H7CX-□-N are no-voltage (short-circuit or open) inputs or voltage inputs.

#### No-voltage Inputs (NPN Inputs)



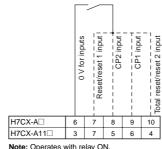




H7CX-A11□ 3

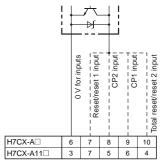
Note: Operates with transistor ON

#### **Contact Input**



Note: Operates with relay ON

#### **DC Two-wire Sensor**



Note: Operates with transistor ON

#### No-voltage Input Signal Levels

No-contact input	$\label{eq:short-circuit level (transistor ON)} \begin{tabular}{ll} Short-circuit level (transistor ON) \\ \bullet Residual voltage: 3 V max. \\ \bullet Impedance when ON: 1 k\Omega max. \\ (The leakage current is approx. 12 mA when the impedance is 0 \Omega.)$
	Open level (transistor OFF) • Impedance when OFF: 100 $k\Omega$ min.
Contact input	Use contacts which can adequately switch 5 mA at 10 V.

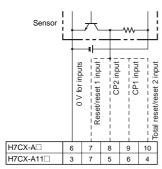
Note: The DC voltage must be 30 VDC max.

#### **Applicable Two-wire Sensor**

- Leakage current: 1.5 mA max.
- · Switching capacity: 5 mA min. • Residual voltage: 3 VDC max.
- Operating voltage: 10 VDC

# **Voltage Inputs (PNP Inputs)**

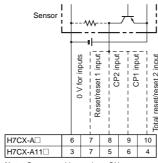
### **No-contact Input (NPN Transistor)**



Note: Operates with transistor OFF.

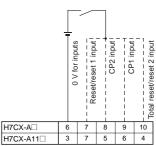
### No-contact Input (PNP Transistor)

10



Note: Operates with transistor ON.

### **Contact Input**



Note: Operates with relay ON.

#### **Voltage Input Signal Levels**

High level (input ON): 4.5 to 30 VDC Low level (input OFF): 0 to 2 VDC

Note: 1. The DC voltage must be 30 VDC max.

2. Input resistance: Approx. 4.7 k $\Omega$ 

### **Nomenclature**

#### **Display Section**

1. Key Protect Indicator (orange)

#### 2. Control Output Indicator (orange)

OUT: (One-stage) OUT: 12 (Two-stage)

3. Reset Indicator (orange)

(Lit when the reset input (1) or Reset Key is ON.) Displayed only when the configuration selection mode is not tachometer mode.

#### 4. Total Count Indicator

(Lit when the total count value is displayed.)

#### 5. Batch Indicator

(Lit when the batch count value is displayed.)

#### 6. Set Value 1, 2 Stage Indicator

#### 7. Present Value (Main Display)

(Character height: 12 mm (6-digit: 10 mm), red\*) \* Characters on models with screw terminals (H7CX-A11□) can be switched between red, green, and orange.

# 8. Set value (Sub-display)

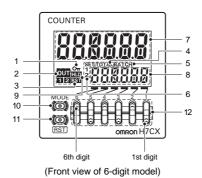
(Character height: 6 mm, green)

#### 9. Hold Display (orange)

Displayed only when the configuration selection mode is not tachometer mode.

# COUNTER 3 10 12 11 4th digit

(Front view of 4-digit model)



#### Operation Keys

#### 10. Mode Key

(Changes modes and setting items.)

#### 11. Reset Key (See note.)

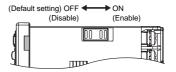
#### 12. Up Keys 1 to 4

(6-digit models: 1 to 6)

#### 13. Down Keys 1 to 4

#### Switches

#### 14. Key-protect Switch



#### 15. DIP Switch



### Model with 4 Digits

Character Size for Main Display









Model with 6 Digits

Character Size for Main Display

Character Size for Sub-display







#### **Note:** The reset functions depends on the selected configuration.

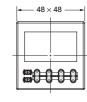
Configuration	Reset operation
1-stage/2-stage preset counter	Resets the present value and outputs.
Total and preset counter	Resets the present value and outputs.  When the total count value is displayed, resets the present value, the total count value, and outputs.
Batch counter	Resets the present value and OUT2. When the batch count value is displayed, resets the present value, the batch count value, and outputs.
Dual counter	Resets the CP1 present value, CP2 present value, dual count value, and outputs.
Twin counter	Resets the CP1 present value and output 1 when the CP1 present value is displayed. Resets the CP2 present value and output 2 when the CP2 present value is displayed.
Tachometer	Holds the measurement value and outputs (hold function). (When the input mode is 2-input independent measurement, the CP1 measurement value display will hold the CP1 measurement value and output 1 and the CP2 measurement value display will hold the CP2 measurement value and output 2.)

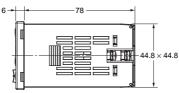
#### **Dimensions** (Unit: mm)

#### **Counters**

#### H7CX-A-N/-AS-N/-AW-N/-AWS-N/-AWD1-N/-AWSD1-N/-A4-N/-A4S-N/-A4W-N/-AU-N/-AUD1-N/-AUSD1-N (Flush Mounting Models)



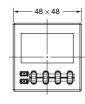


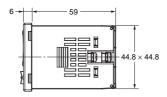


Note: M3.5 terminal screw (effective length: 6 mm)

#### H7CX-AD-N/-ASD-N/-AWSD-N/-A4D-N/-A4SD-N/-A4WSD-N (Flush Mounting Models)



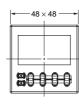


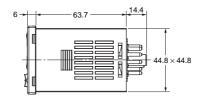


Note: M3.5 terminal screw (effective length: 6 mm)

#### H7CX-A11-N/-A11S-N/-A11D1-N/-A11SD1-N/-A114S-N/-A114D1-N (Flush Mounting/Surface Mounting Models)

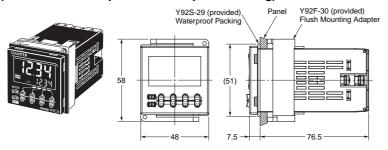




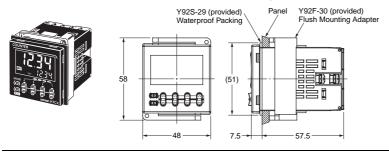


#### **Dimensions with Flush Mounting Adapter**

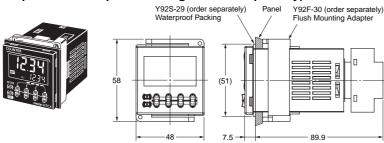
# H7CX-A-N/-AS-N/-AW-N/-AWS-N/-AWD1-N/-AWSD1-N/-A4-N/-A4S-N/-A4W-N (Provided with Adapter and Waterproof Packing)



# H7CX-AD-N/-ASD-N/-AWSD-N/-A4D-N/-A4SD-N/-A4WSD-N (Provided with Adapter and Waterproof Packing)

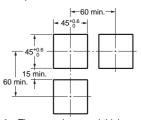


H7CX-A11-N/-A11S-N/-A11D1-N/-A11SD1-N/-A114-N/-A114S-N/-A114D1-N (Adapter and Waterproof Packing Ordered Separately)



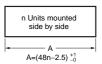
#### **Panel Cutouts**

Panel cutouts are as shown below. (according to DIN43700).



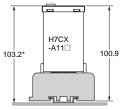
Note: 1. The mounting panel thickness should be 1 to 5 mm.

- To allow easier operation, it is recommended that Adapters be mounted so that the gap between sides with hooks is at least 15 mm (i.e., with the panel cutouts separated by at least 60 mm).
- It is possible to mount counters side by side, but only in the direction without the hooks. If they are mounted side-by-side, waterresistance will be lost.



With Y92A-48F1 attached. A= $\{48n-2.5+(n-1)\times4\}_{0}^{+1}$  With Y92A-48 attached. A= $\{51n-5.5\}_{0}^{+1}$ 

# Dimensions with Front Connecting Socket



P2CF-11(-E) Front Connecting Socket (order separately)

<sup>\*</sup> These dimensions depend on the kind of DIN Track. (Reference value)

### **Accessories (Order Separately)**

Note: Depending on the operating environment, the condition of resin products may deteriorate, and may shrink or become harder. Therefore, it is recommended that resin products are replaced regularly.

#### Front Panel (Replacement Part)

You can change the color of the Front Panel when mounting the Counter/Tachometer. The Counter/Tachometer is shipped with a black (N1.5) Front Panel. "COUNTER" is printed on the front of Replacement Front Panels.

#### Y92P-CXC4G

4-digit Counter Light gray (5Y7/1)

#### Y92P-CXC4S

4-digit Counter White (5Y9.2/0.5)

#### Y92P-CXT4B

4-digit Counter Black (N1.5)

#### Y92P-CXT6G

6-digit Counter Light gray (5Y7/1)

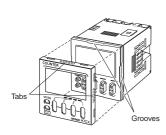
#### Y92P-CXT6S

6-digit Counter White (5Y9.2/0.5)

#### Y92P-CXT6B

6-digit Counter Black (N1.5)

#### **Replacement Method**



The Front Panel is attached to the Counter/Tachometer with tabs in four locations. To remove the Front Panel, open the tabs and pull the Front Panel forward. To attach the Front Panel, press it onto the Counter/Tachometer so that all four tabs lodge into the grooves on the body of the Counter/Tachometer.

#### Soft Cover Y92A-48F1

#### Hard Cover Y92A-48



# Protecting the Counter/Tachometer in Environments Subject to Oil

The H7CX's panel surface is water-resistive (conforming to IP□6, UL Type 4X) and so even if drops of water penetrate the gaps between the keys, there will be no adverse effect on internal circuits. If, however, there is a possibility of oil being present on the operator's hands, use the Soft Cover. The Soft Cover ensures protection equivalent to IP54F against oil. Do not, however, use the H7CX in locations where it would come in direct contact with oil.

#### Flush Mounting Adapter Y92F-30

#### Y92F-45

Order the Flush Mounting Adapter with the following model number separately if it is lost or damaged. **Note:** The

The Waterproof Packing is included with models with screw terminals.



Use this Adapter to install the Counter/ Tachometer in a cutout previously made for a DIN 72  $\times$  72 mm device (panel cutout: 68  $\times$  68 mm).



# Waterproof Packing Y92S-29

Note: The

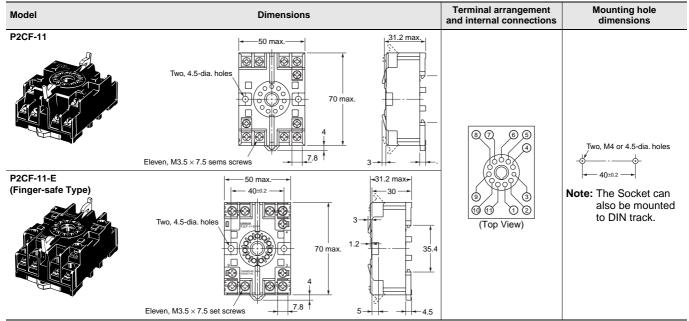
Waterproof Packing is included with models with screw terminals.



Order the Waterproof Packing separately if it is lost or damaged. The Waterproof Packing can be used to achieve IP66 protection.

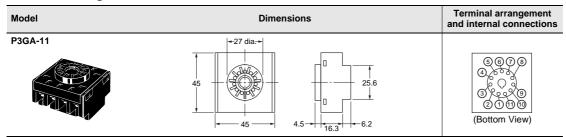
The Waterproof Packing will deteriorate, harden, and shrink depending on the application environment. To ensure maintaining the IP $\Box$ 6, UL Type 4X waterproof level, periodically replace the Waterproof Packing. The periodic replacement period will depend on the application environment. You must confirm the proper replacement period. Use 1 year or less as a guideline. If the Waterproof Packing is not replaced periodically, the waterproof level will not be maintained. It is not necessary to mount the Waterproof Packing if waterproof construction is not required.

# **Connection Sockets**Front Connecting Socket



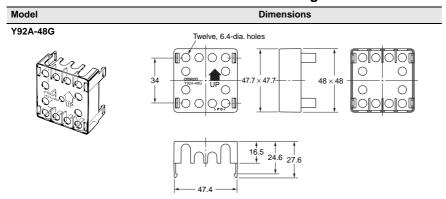
Note: Round crimp terminals cannot be used on Finger-safe Sockets. Use forked crimp terminals.

#### **Back-connecting Sockets**



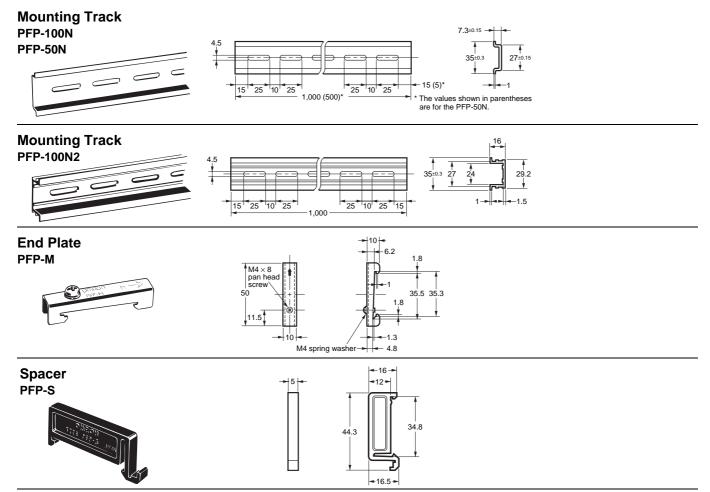
Note: A Y92A-48G Terminal Cover can be used with the Socket to create a finger-safe construction.

#### **Terminal Covers for P3GA-11 Back-connecting Socket**



Note: The Terminal Cover can be used with a Back-mounting Socket (P3GA-11) to create a finger-safe construction.

# **Optional Products for Track Mounting**



Note: Order Spacers in increments of 10.

## **Operating Procedures**

#### **Setting Procedure Guide**

**Setting for Counter Operation \*** 

Use the following settings.

#### **Setting for Tachometer Operation \***

Refer to page page 27.

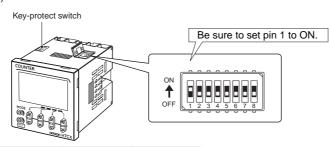
\* At the time of delivery, the H7CX is set to the 1-stage preset counter configuration. (2-stage models are set to the 2-stage preset counter configuration.) Refer to page page 35 for information on switching models.

### I/O Functions for Counter Operation



Set the basic parameters.

(If the desired I/O mode is not listed below or to set all parameters using the front panel keys, perform Step3, below.)



1         DIP switch settings         Disabled         Enabled           2         Counting speed         30 Hz         5 kHz           3         Input mode         UP         DOWN           4         Output mode         Refer to the table on the right.           6         Output time         0.5 s         0.05 s           7         Minimum reset signal         20 ms         1 ms		Item	OFF	ON	
3         Input mode         UP         DOWN           4         Output mode         Refer to the table on the right.           6         Output time         0.5 s         0.05 s	1	DIP switch settings	Disabled	Enabled	
4 Output mode Refer to the table on the right. 6 Output time 0.5 s 0.05 s	2	Counting speed	30 Hz	5 kHz	
Output mode Refer to the table on the right.  Output time 0.5 s 0.05 s	3	Input mode	UP	DOWN	
5 0.05 s 0.05 s	4	Output mode	Refer to the table on the right.		
5 554 555	5	Output mode			
7 Minimum reset signal 20 ms 1 ms	6	Output time	0.5 s	0.05 s	
	7	Minimum reset signal	20 ms	1 ms	
8 Input selection NPN PNP	8	Input selection	NPN	PNP	

Pin 4	Pin 5	Output mode
OFF	OFF	N
ON	OFF	F
OFF	ON	С
ON	ON	K-1

Note: All pins are factory-set to OFF.

- When setting functions using the DIP switch, be sure to set pin 1 of the DIP switch to ON.
- DIP switch settings are effective when the power is turned ON again. (Perform DIP switch settings while the power is OFF.)



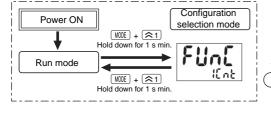
# Step2

The H7CX-A□-N is a Counter that contains more than one functional counter.

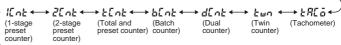
When using the Counter in any mode other than the default mode\*, use the following chart to enter Configuration Selection Mode and set the functions that are suitable to the application.

\* The default mode is 1-stage preset counter configuration (2-stage preset counter configuration for 2-stage models).

Note: Step2 can be performed first, followed by Step1.



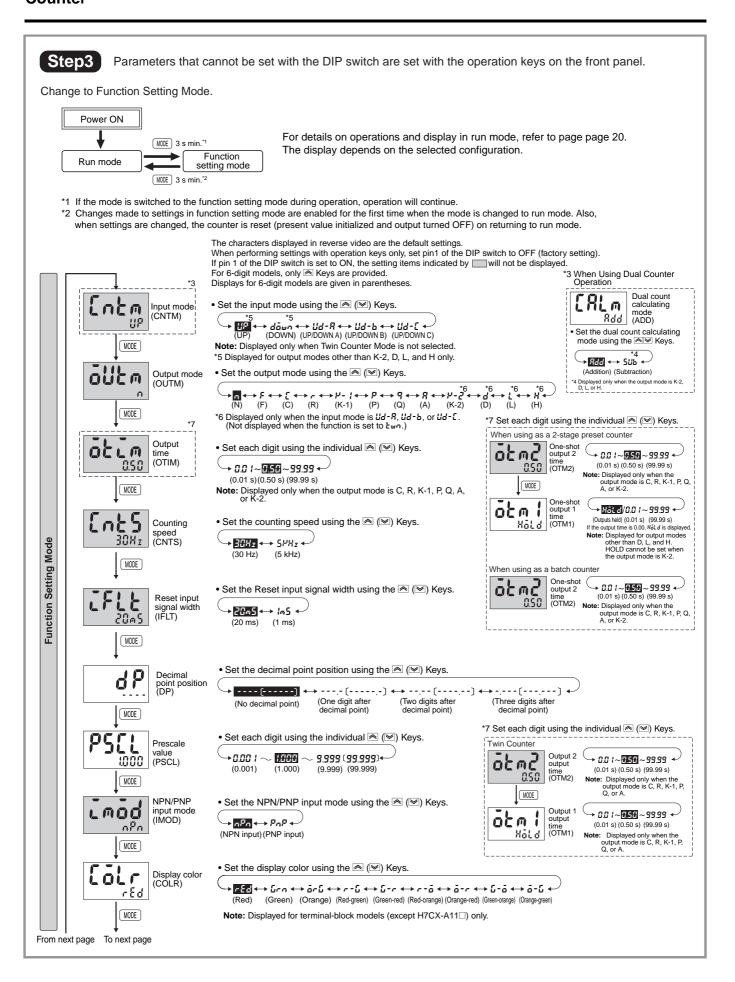
Select the function from Table 1 using the  $\ \ \ \ \,$  ( $\ \ \ \ \ \,$  ) Key.

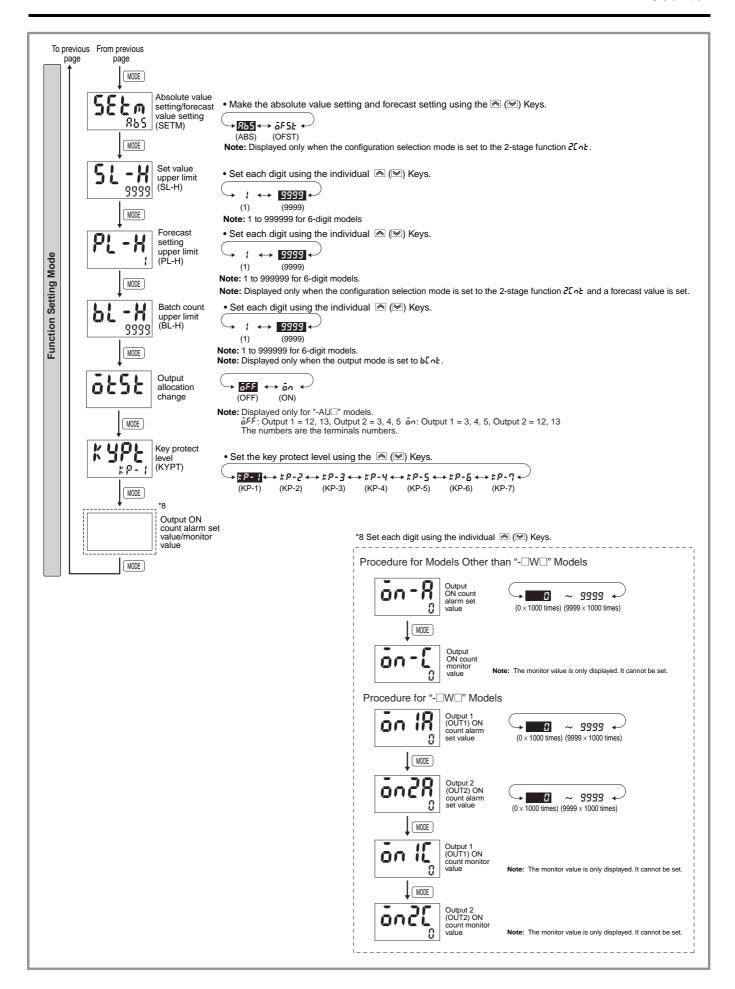


Note: The configuration that can be selected depends on the model



After making DIP switch settings for basic operations, advanced functions can be added using the operation keys. For details, refer to page page 16.





#### **Explanation of Functions**

Items marked with stars ★ can be set using the DIP switch.

#### Input Mode ([n≿n)★

Set increment mode (UP), decrement mode (DOWN), or one of the increment/decrement modes (UP/DOWN A, UP/DOWN B, or UP/DOWN C) as the input mode.

Input modes other than UP or DOWN modes cannot be set using the DIP switch and so use the operation keys if other modes are required. (For details on the operation of the input modes, refer to *Input Modes and Present Value* on page page 21.)

#### Dual Count Calculating Mode ([RLn])

When using as a dual counter, select either ADD (addition) or SUB (subtraction) as the calculation method for the dual count value.

ADD: Dual count value = CP1 PV + CP2 PV

SUB: Dual count value = CP1 PV - CP2 PV

#### Output Mode (Ճեհա)★

Set the way that control output for the present value is output. The possible settings are N, F, C, R, K-1, P, Q, A, K-2, D, L, and H. Output modes other than N, F, C, or K-1 cannot be set using the DIP switch and so use the operation keys if other modes are required. The output modes that can be set vary with the model.

(For details on the operation of the output modes, refer to *Input/Output Mode Settings* on page page 22.)

#### One-shot Output Time (å₺₡₼)★

Set the one-shot output time (0.01 to 99.99 s) for control output. One-shot output can be used only when C, R, K-1, P, Q, A, or K-2 is selected as the output mode. Output times other than 0.5 s or 0.05 s cannot be set with the DIP switch and so use the operation keys if other settings are required.

#### One-shot Output 2 Time (å₺₼₢)★

Set the one-shot output time (0.01 to 99.99 s) for control output (OUT2).

One-shot output can be used only when C, R, K-1, P, Q, A, or K-2 is selected as the output mode. Output times other than 0.5 s or 0.05 s cannot be set with the DIP switch and so use the operation keys if other settings are required.

#### One-shot Output 1 Time (å t n l)

Set the one-shot output time (0.01 to 99.99 s) for control output (OUT1).

One-shot output can be used only when D, L, or H is selected as the output mode.

If the output time is set to 0.00, HoLd is displayed, and outputs are

#### Counting Speed ([n≥5)★

Set the maximum counting speed (30 Hz/5 kHz) for CP1 and CP2 inputs together.

If contacts are used for input signals, set the counting speed to 30 Hz. Processing to eliminate chattering is performed for this setting.

#### Reset Input Signal Width (LFLE)★

Set the reset input signal width (20 ms/1 ms) for reset/reset 1 and total reset/reset 2 inputs together.

If contacts are used for the input signal, set the input signal width to 20 ms. Processing to eliminate chattering is performed for this setting.

#### Decimal Point Position (dP)

Decide the decimal point position for the present value, CP1/CP2 present values, set value (SV1, SV2), total count value, and dual count set value.

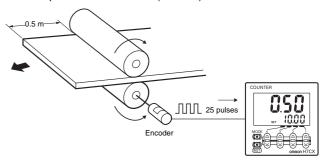
#### Prescale Value (PSLL)

Pulses input to the counter are converted according to the specified prescale value.

(Setting range: 0.001 to 99.999 for 6-digit models and 0.001 to 9.999 for 4-digit models.)

Example: To display the feed distance for systems that output 25 pulses for a feed length of 0.5 m in the form  $\square\square.\square\square$  m:

- 1. Set the decimal point position to 2 decimal places.
- 2. Set the prescale value to  $0.02 (0.5 \div 25)$ .



Observe the following points when setting a prescale value.
 Set the set value to a value less than {Maximum countable value – Prescale value}.

Example: If the prescale value is 1.25 and the counting range is 0.000 to 999.999, set the set value to a value less than 998.749 (= 999.999 - 1.25).

If the set value is set to a value greater than this, output will not turn  $\ensuremath{\mathsf{ON}}.$ 

 Output will turn ON, however, if a present value overflow occurs (FFFFF or FFFF).

Note: If the prescale value setting is incorrect, a counting error will | occur. Check that the settings are correct before using this | function.

#### NPN/PNP Input Mode (เัตอ์ฮ์)

Select either NPN input (no-voltage input) or PNP input (voltage input) as the input format. When using a two-wire sensor, select NPN input.

The same setting is used for all external inputs.

For details on input connections, refer to *Input Connections* on page page 9.

# Display Color ( $\tilde{Lal}$ -r) (Displayed for terminal block models (except H7CX-A11 $\square$ ) only.)

Set the color used for the present value.

	Output OFF*	Output ON*		
rEd	Red (	fixed)		
Gra	Green	(fixed)		
ŏrū	Orange (fixed)			
r-G	Red	Green		
G-r	Green	Red		
r-ă	Red	Orange		
ŏ-r	Orange	Red		
ű-ŏ	Green	Orange		
ŏ-G	Orange Green			

\* Output 2 for 2-stage models.

With the twin counter, output 1 and output 2 will both turn OFF when the output status is OFF. Either output 1 or output 2 will turn ON when the output status is ON.

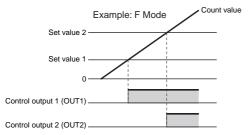
#### Absolute Value Setting/Forecast Value Setting (5EEm)

For the 2 count output mode, an absolute value setting (Rb5) or forecast value setting ( $\tilde{a}F5k$ ) can be set for set value 1.

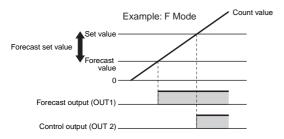
When a forecast value is set, specify the forecast value set value (i.e., the deviation for the set value).

The forecast output (output 1) turns ON when the present value reaches the forecast value.

If the forecast set value is greater than or equal to the set value, the forecast output (output 1) will turn ON as soon as counting starts.



If the forecast value setting is used, specify the set value 2 minus the forecast value setting for set value 1.



#### Set Value Upper Limit (5½ - H)

Set the upper limit for the set value when it is set in run mode. The setting can be made from 1 to 9999 for 4-digit models and from 1 to 999999 for 6-digit models.

#### Forecast Set Upper Limit (PL -H)

Set the upper limit for the forecast set value.

The setting can be made from 1 to 9999 for 4-digit models and from 1 to 999999 for 6-digit models.

#### Batch Count Upper Limit (54 - 4)

Set the upper limit for the batch count value. The setting can be made from 1 to 9999 for 4-digit models and from 1 to 999999 for 6-digit models.

#### Output Allocation (5£5£)

When using an H7CX-AU□-N model as a 2-stage counter, the output can be flexibly allocated to either stage 1 or 2.

The transistor output can be allocated to SV1 and the contact output to SV2 or vice verse, as in the following tables.

#### H7CX-AU-N/-AUD1-N

	Output 1	Output 2	
Transistor (12-13)		Contact (3, 4, 5)	
ŏn	Contact (3, 4, 5)	Transistor (12-13)	

#### H7CX-AUSD1-N

	Output 1	Output 2
Transistor (12-13)		Transistor with diode (3, 4, 5)
ěα	Transistor with diode (3, 4, 5)	Transistor (12-13)

#### Key Protect Level (# 남부분)

Set the key protect level.

Refer to Key Protect Level on page page 36.

#### Output ON Count Alarm Set Value (50-8)

Set the alarm value for the output ON count.

The limit can be set to between  $\underline{0} \times 1000$  (0 times) and  $\underline{9999} \times 1000$  (9,999,000 times). Only the underlined values are set. The alarm will be disabled if 0 is set.

If the total ON count of the output exceeds the alarm set value, £3 will be displayed on the Timer to indicate that the output ON count alarm value was exceeded. Refer to *Self-diagnostic Function* on page page 36 for information on the £3 display.

# ON Count Alarm Set Values for Outputs 1 and 2 (OUT1 and OUT2) (อัก ให้ and อักอีหี)

Set the ON count alarm values for the outputs 1 and 2.

The limit can be set to between  $\underline{0} \times 1000$  (0 times) and  $\underline{9999} \times 1000$  (9,999,000 times). Only the underlined values are set. The alarm will be disabled if 0 is set.

If the total ON count of instantaneous output 1 or 2 exceeds the alarm set value, £3 will be displayed on the Timer to indicate that the output ON count alarm value was exceeded. Refer to Self-diagnostic Function on page page 36 for information on the £3 display.

#### Output ON Count Monitor Value (an-[)

The monitor value is only displayed. It cannot be set.

The output ON count will be 1,000 times the displayed value.

# ON Count Monitor Values for Outputs 1 and 2 (OUT1 and OUT2) (an IE and and E)

The monitor value for output 1 or 2 is only displayed. It cannot be set. The output ON count will be 1,000 times the displayed value.

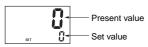
### **Operation in Run Mode**

#### I/O Functions for Counter Operation

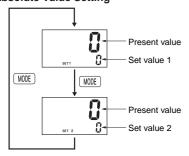
• Set values for each digit as required using the <a> (♥)</a> Keys. (♠ Key only for 6-digit models.)



#### 1-stage Preset Counter



#### 2-stage Preset Counter with Absolute Value Setting

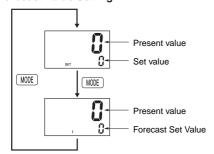


Present Value
 Shows the present count value.

# Set Values (Set Value 1 and Set Value 2) Set the set values.

When the present value reaches the set value (set value 1 or set value 2), a signal is output according to the specified output mode.

# 2-stage Preset Counter with Forecast Value Setting



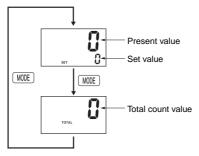
- Present Value
  - Shows the present count value.
- Set Values

Set the set values.

#### • Forecast Set Value

Set the deviation for the set value.

#### **Total and Preset Counter**



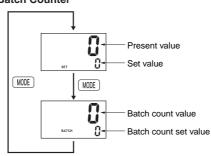
Present Value/Set Value

Same as 1-stage preset counter.

Total Count Value

Shows the present total count value.

#### **Batch Counter**



#### • Present Value/Set Value

Same as 1-stage preset counter.

#### Batch Count Value

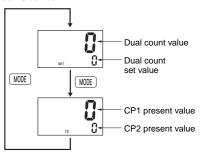
Shows the number of times the count has been completed for the present value.

#### Batch Count Set Value

Set the batch count set value.

When the batch count value reaches the batch count set value, batch output (OUT1) turns ON.

#### **Dual Counter**



#### Dual Count Value

Shows the sum of the CP1 present value and CP2 present value when the dual count calculating mode is ADD and shows the value obtained by subtracting the CP2 present value from the CP1 present value when the dual count calculating mode is SUB.

#### • Dual Count Set Value

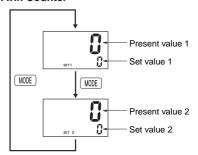
Set the dual count set value.

When the dual count value reaches the dual count set value, signals are output according to the specified output mode.

#### CP1/CP2 Present Value

Show the present count values for CP1 and CP2 present values respectively.

#### Twin Counter



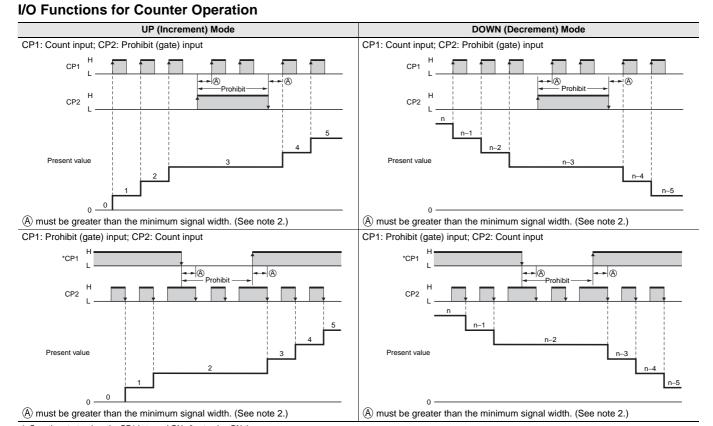
Present Values 1 and 2

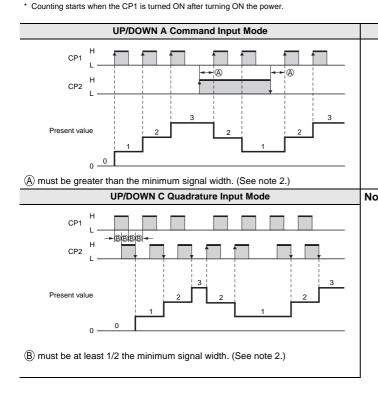
Shows the present count value 1 or 2.

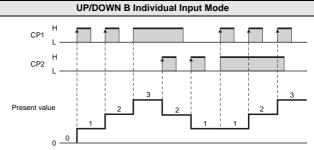
• Set Values 1 and 2

Setting for present value 1 or 2.

# Input Modes and Present Value (See note 1.)







- Note: 1. If the configuration selection is set to dual counter, CP1 and CP2 input will operate in the same way as the count input (CP1) of UP (increment) mode.
  - 2. A must be greater than the minimum signal width and B must be at least 1/2 the minimum signal width. If they are less, a count error of  $\pm 1$  may occur. Minimum signal width: 16.7 ms (when maximum counting speed = 30 Hz) 100  $\mu$ s (when maximum counting speed = 5 kHz)
  - The meaning of the H and L symbols in the tables is explained below.

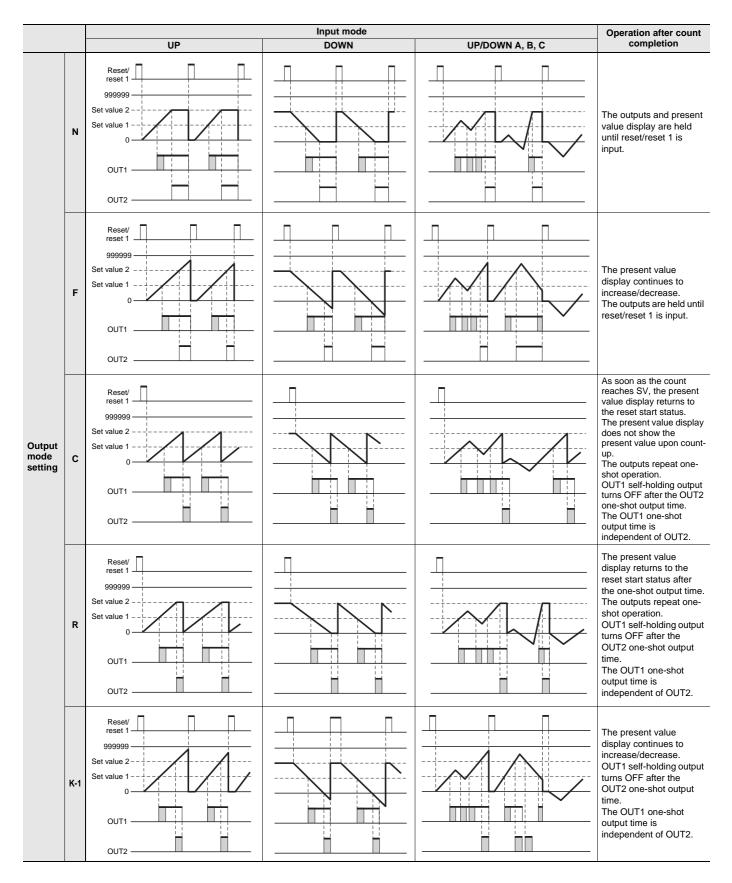
Symbol Input method	No-voltage input (NPN input)	Voltage input (PNP input)
Н	Short-circuit	4.5 to 30 VDC
L	Open	0 to 2 VDC

### **Input/Output Mode Settings**

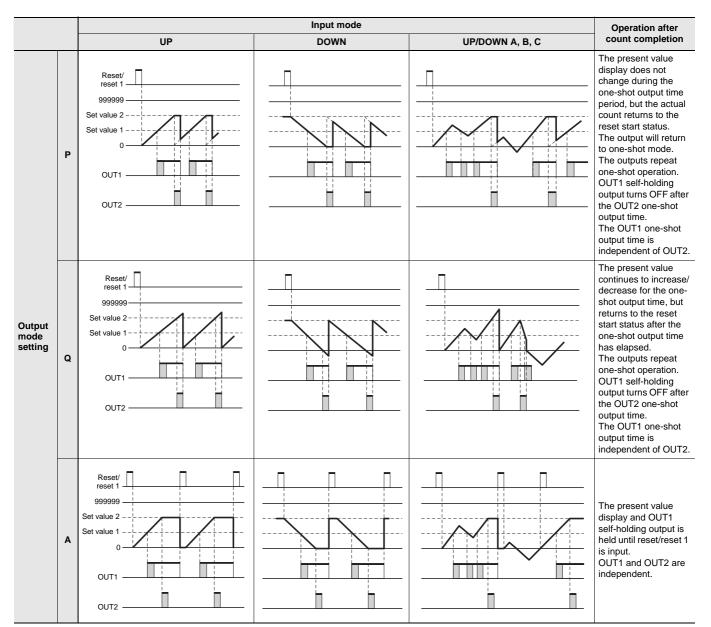
#### I/O Functions for Counter Operation

If a 1-stage model or 2-stage model is incorrectly used as twin counter, the operation for output 2 will be performed. When using a 2-stage model as a 1-stage preset counter, total and preset counter, or dual counter, OUT1 and OUT2 turn ON and OFF simultaneously.





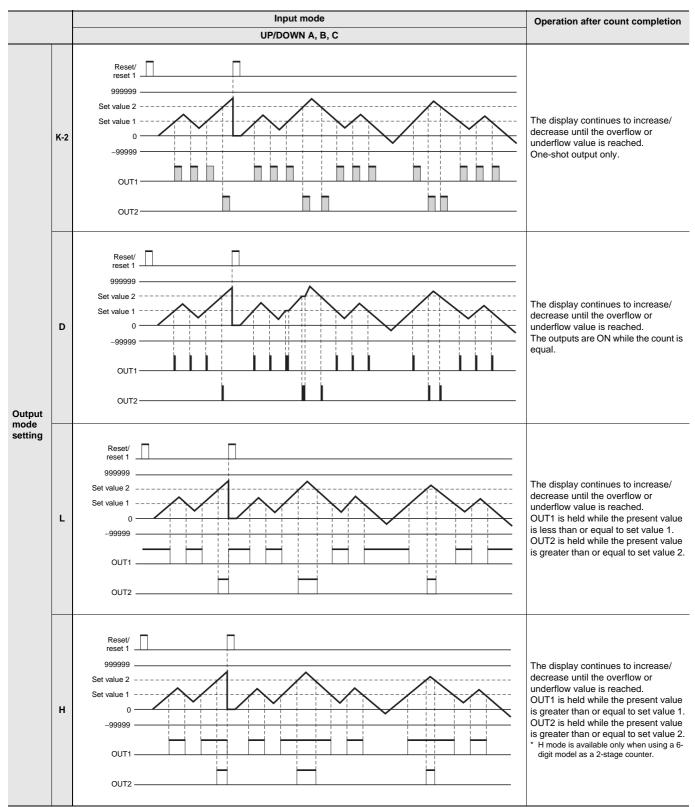




Note: 1. The full scale (FS) for H7CX 4-digit models is 9999.

- 2. When the present value reaches 999999, it returns to 0.
- 3. Counting cannot be performed during reset/reset 1 input.
- 4. If reset/reset 1 is input while one-shot output is ON, one-shot output turns OFF.
- 5. If there is power failure while output is ON, output will turn ON again when the power supply has recovered. For one-shot output, output will turn ON again for the duration of the output time setting once the power supply has recovered.
- 6. Do not use the counter function in applications where the count may be completed (again) while one-shot output is ON.
- 7. The setting range is 0 to 999,999 (0 to 9,999 for 4-digit models).

Self-holding Instantaneous output (equals) out

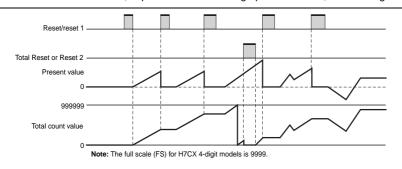


Note: 1. Counting cannot be performed during reset/reset 1 input.

- 2. If reset/reset 1 is input while one-shot output is ON, one-shot output turns OFF.
- 3. If there is power failure while output is ON, output will turn ON again when the power supply has recovered. For one-shot output, output will turn ON again for the duration of the output time setting once the power supply has recovered.
- 4. Do not use the counter function in applications where the count may be completed (again) while one-shot output is ON.
- 5. The set value is from -99999 to 999999.

#### **Total and Preset Counter Operation**

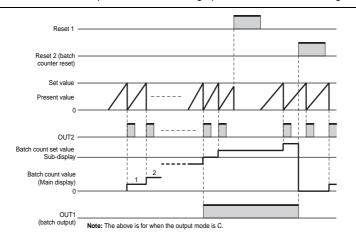
The H7CX has a total counter, separate from the 1-stage preset counter, for counting the total accumulated value.



- The total counter continues to count the total accumulated value when the present value is reset using reset/reset 1 input (Reset Key).
- The total count value is reset when the total reset/reset 2 input is turned ON. If the Reset Key is pressed while the total count value is displayed, the total count value is reset. The present value is also reset at this time.
- The counting range of the total counter is -99,999 to 999,999 (-999 to 9,999). The total count value returns to 0 when it reaches the full scale limit.

#### **Batch Counter Operation**

The H7CX has a batch counter, separate from the 1-stage preset counter, for counting the number of times the count has been completed.



- The batch counter continues after count completion.
- · Batch output is held until batch counter reset is input.
- · When the batch counter reset input is turned ON, the batch count value is reset, and batch output turns OFF.
- . If the Reset Key is pressed while the batch count value is displayed, the batch count value is reset and batch output turns OFF. The present value is also reset at this time.
- The count value can be incremented and decremented.
- The batch count is only incremented.
- The maximum counting speed for batch counter operation is 5 kHz. The batch counter counts the number of times the count reaches the set

- Note: The batch count value is held at 0 during batch counter reset input.

(2) Dual Count Calculating Mode = SUB

The batch count value is neid at 0 during batch counter reset input.

If the batch count set value is 0, batch count will be performed but there will be no batch output.

The batch count value returns to 0 when it reaches 999,999 (9,999 for 4-digit models).

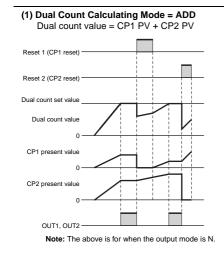
Once batch input has been turned ON, it will return to the ON state after power interruptions.

If the batch count set value is changed from a value that is greater than the batch count value to one that is less, batch output will turn ON.

After batch output turns ON, the ON state will be held even if the batch count set value is changed to a value greater than the batch count value.

#### **Dual Counter Operation**

Using the dual counter allows the count from 2 inputs to be added or subtracted and the result displayed. It is possible to specify a set value for which output turns ON when the set value matches the added or subtracted result.



Dual count value = CP1 PV - CP2 PV Reset 1 (CP1 reset) Reset 2 (CP2 reset) Dual count set value CP1 present value CP2 present value

OUT1, OUT2

**Note:** The above is for when the output mode is K-2. SUB mode can be used only when K-2, D, L, or H is selected as the output mode with 6-digit models.

- The operation after count completion for the dual counter value is determined by the output mode.
- The CP1 present value is reset when reset 1 input is turned ON.
- The CP2 present value is reset when reset 2 input is turned ON.
- If the Reset Key is pressed while the dual count value, CP1 present value, or CP2 present value is displayed, all of the present values are reset and outputs turn OFF. At this time, counting is not possible for CP1 or CP2 inputs.
- Counting is not possible for CP1 during reset 1 input. CP2 will not be affected. The dual count value will be calculated based on a CP1 present value of 0. Counting is not possible for CP2 during reset 2 input. CP1 will not be affected. The dual count value will be calculated based on a CP2 present value of 0. The counting range for the dual count value is –99,999 to 999,999 (0 to 9,999 for 4-digit models). The counting ranges for the CP1 present value and CP2 present value are 0 to 999,999 (0 to 9,999 for 4-digit models). If a present value exceeds 999,999 (9,999 for 4-digit models), FFFFF (FFFF for 4-digit models) will be displayed to indicate an overflow, and all counting will store. will stop.

# H7CX-A□-N Counter

#### **Twin Counter Operation**

Two independent counters are built in.

	Counter 1	Counter 2		
Counter input	CP1	CP2		
Reset input	Reset 1	Reset 2		
Present value display and setting	Counter 1 display  Counter 1 present value  Switched the MODE A	SFT 2 L L		
Reset Key	Only counters appearing o	n the display will be reset.		

Note: 1. Only 2-stage models

- 2. Increment mode only for counters 1 and 2.
- 3. The settings for prescaling and the decimal point are used by both counter 1 and 2.

#### **Reset Function List**

### I/O Functions for Counter Operation

Function	1-stage/2- stage preset counter	Total and pr	eset counter	Batch counter		Dual counter		Twin counter		
Screen dis- played in run mode	Present value/ set value (1, 2)	Present value/set value	Total count value	nt Present value/set value value		Dual count value/dual count set value	CP1 present value/CP2 present value	Present value 1/Set value 1	Present value 2/Set value 2	
Reset/reset 1	Present value and output reset.		e and output set.		Present value and output reset.		Only the CP1 present value is reset.		Only the CP1 present value is reset.	
Total reset or reset 2	No effect	,	count value is set.	Batch count value and batch output reset.		Only the CP2 present value is reset.		Only the CP2 present value is reset.		
Reset Key	Present value and output reset.	Present value and output reset.	Present value, total count value, and output reset.	Present value and output reset.	Present value, batch count value, output and batch output reset.	present valu	nt value, CP2 ne, dual count output reset.	CP1 present value reset	CP2 present value reset	

• The following table shows the delay from when the present value passes the set value until the output is produced.

### Actual measurements in N and K-2 modes (Reference values)

Control output type	Max. counting speed	Output delay time
Contact output	30 Hz	16.5 to 24.0 ms
Contact output	5 kHz	3.7 to 5.6 ms
Transistor output	30 Hz	12.0 to 20.0 ms
Transistor output	5 kHz	0.2 to 0.55 ms

Note: The above times may vary slightly depending on the mode or operating conditions.

### **Setting Procedure Guide**

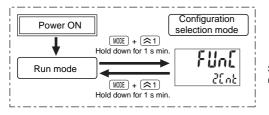
### **Tachometer Operation**



The H7CX is factory-set to the 2-stage counter configuration (1-stage counter configuration for  $H7CX-AU\square-N$  models).

Enter configuration selection mode using the following chart and set the tachometer mode.

Note: Step2 can be performed first, followed by Step1 .



Switch from <code>2Enb</code> (2-stage preset counter mode) to <code>ERE</code> is (tachometer mode) using the A Key.

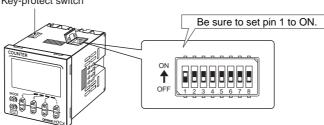


# Step2

Set the basic parameters.

(If the desired I/O mode is not listed below or to set all parameters using the front panel keys, perform Step3

below.) Key-protect switch



		item	OFF	ON		PIII 3	PIN 4	rachometer output mode
	1	DIP switch settings	Disabled	Enabled		OFF	OFF	Upper/lower limit output
	2	Counting speed	30 Hz	10 kHz	_	ON	OFF	Range output
	3	Table	Defeated to the		$\bot$	OFF	ON	Upper limit output
	4	Tachometer output mode	Refer to the table on the right.			ON	ON	Lower limit output
5								
	6	Average processing	Refer to the table on the right.		$\neg$	Pin 5	Pin 6	Average processing
	7					OFF	OFF	OFF
8 Input selection NPN PNP					L	ON	OFF	2 times
Note: All pins are factory-set to OFF.						OFF	ON	4 times
	•					ON	ON	8 times

- When setting functions using the DIP switch, be sure to set pin 1 of the DIP switch to ON.
- DIP switch settings are effective when the power is turned ON again. (Perform DIP switch settings while the power is OFF.)

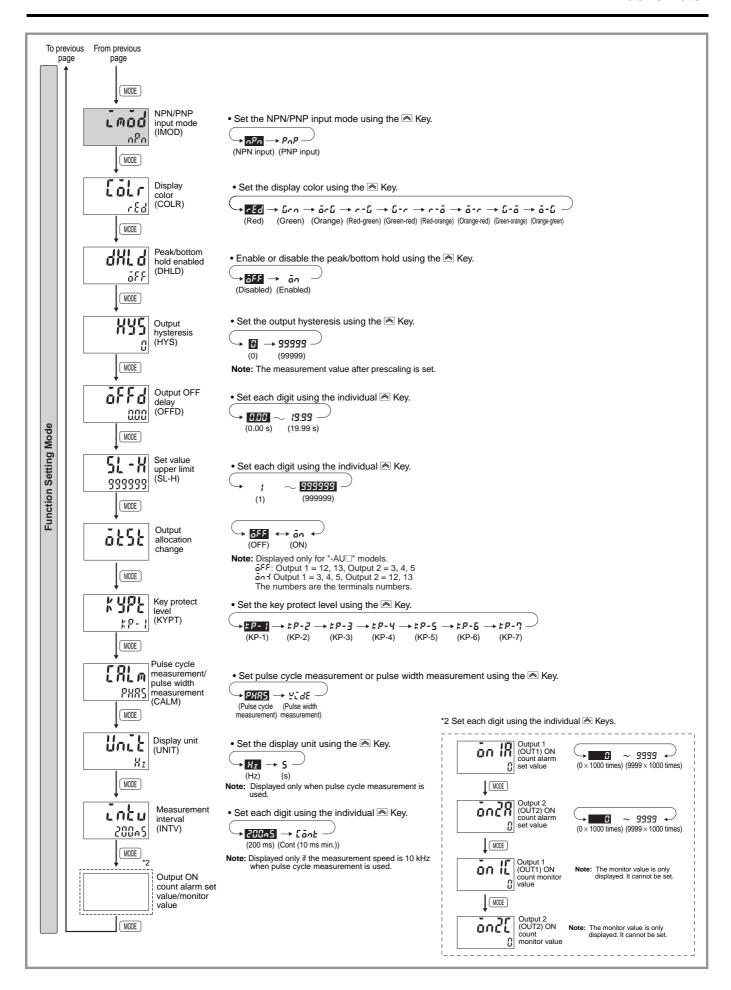


After making DIP switch settings for basic operations, advanced functions can be added using the operation keys. For details, refer to page page 28.

Step3 Parameters that cannot be set with the DIP switch are set with the operation keys on the front panel. Change to Function Setting Mode. For details on operations and display in run mode, refer to page page 33. Power ON MODE 3 s min.\*1 Function Run mode setting mode MODE 3 s min.\*2 \*1 If the mode is switched to the function setting mode during operation, operation will continue. \*2 Changes made to settings in function setting mode are enabled for the first time when the mode is changed to run mode. Also, when settings are changed, the counter is reset (measured value initialized and outputs turned OFF) on returning to run mode. The characters displayed in reverse video are the default settings. When performing settings with operation keys only, set pin1 of the DIP switch to OFF (factory setting). If pin 1 of the DIP switch is set to ON, the setting items indicated by will not be displayed. Tachometer • Set the tachometer input mode using the A Key. Եւոտ input mode (TINM) F !  $FI \rightarrow F2 \rightarrow F3 \rightarrow F4 \rightarrow F5 -$ \*1 Set tachometer output modes 1 and 2 using the 

in Key. (1 input) (2 inputs) (Error) (Absolute ratio) (Error ratio) MODE Displayed only when the tachometer input mode is F2 (2 inputs). Tachorne output mode 1 (TO1M) Tachometer Hi - Lo Tachometer output mode • Set the tachometer output mode using the A Key. (HI) HILE (TOTM) (LO)  $HLL_0 \longrightarrow RrER \longrightarrow HLHL \longrightarrow LOLO$ (AREA) (HI-HI) (LO-LO) MODE MODE Tachometer → HE → Lō → output mode 2 (TO2M) [n65 Counting • Set the counting speed using the A Key. (CNTS) 30Xz 30Hz → 10PHz (30 Hz) (10 kHz) MODE Note: Even if 10 kHz is selected when the tachometer input mode is F2 to F5, the counting speed will be 5 kHz. dP Decimal point • Set the decimal point position using the A Key. position (DP) **Function Setting Mode** (No decimal point) (One digit after decimal point) (Two digits after (Three digits after (Four digits after decimal point) decimal point) decimal point)

Note: "------" will be displayed when pulse width measurement is set or when the display unit is set to seconds. MODE PSCL Prescale • Set each digit using the individual A Key. value (PSCL) 1000 st0.00 l  $\sim$  1.000  $\sim$  99.999 (0.001) (1.000) (99.999) MODE ռոնե Averaging method Set the averaging method using the Key. Smp (AVGT) 5AP - AU (Simple (Moving averaging) average) MODE Average processing ក្រកាប្រ Set the number of averaging times using the Key. (AVGN) 6FF → *BFF* → 2 → 4  $\rightarrow$  8  $\rightarrow$  15 (No average (Average of 2 (Average of 4 (Average of 8 (Average of 16 processing) measurements) measurements) measurements) measurements) measurements) MODE Auto-zero time • Set each digit using the individual A Key. 9999 (AUT00)  $\star$  C. I  $\sim$  999.9 (0.1 s) (999.9 s) MODE Star Startup time • Set each digit using the individual 🖎 Key. (STMR) 0.0**>##** ∼ 99.9 (0.0 s) (99.9 s) MODE From next page To next page



# Explanation of Functions Tachometer Operation

Items marked with stars ★ can be set using the DIP switch.

#### Tachometer Input Mode (ELOA)

Set the count input mode to one of the following: 1 input ( $^{\mathcal{F}}$   $^{\mathcal{I}}$ ), 2 inputs ( $^{\mathcal{F}}$ 2), error ( $^{\mathcal{F}}$ 3), absolute ratio ( $^{\mathcal{F}}$ 4), or error ratio ( $^{\mathcal{F}}$ 5).

Input mode	Input	Internal processing	Application
1 input	Count 1	None	Operation with only one input.
2 inputs	Counts 1 and 2	None	Operation with two independent inputs.
Error	Counts 1 and 2	Count 1 input – Count 2 input	Measuring the difference between two inputs (error in number of revolutions).
Absolute ratio	Counts 1 and 2 Count 1 input Count 2 input		Measuring the ratio of two inputs (ratio of number of revolutions).
Error ratio	Counts 1 and 2	(Count 1 input – Count 2 input) ÷ Count 2 input	Measuring the ratio of error for two inputs (measuring the error ratio of number of revolutions).

#### Tachometer Output Mode (ŁāŁ⋒)★

Set the output method for control output based on the comparison value. Upper and lower limit (HI-LO), area (AREA), upper limit (HI-HI), and lower limit (LO-LO) can be set.

(For details on the output modes, refer to *Output Mode Settings and Operation* on page page 34.)

#### Counting Speed ([n≥5)★

Set the maximum counting speed (30 Hz/10 kHz) for CP1 input. If contacts are used for input signals, set the counting speed to 30 Hz. Processing to eliminate chattering is performed for this setting.

#### Decimal Point Position (dp)

Decide the decimal point position for the measurement value, OUT1 set value, and OUT2 set value.

#### Prescale Value (PSEL)

It is possible to display the rate of rotation or the speed of a device or machine to which the H7CX is mounted by converting input pulses to a desired unit.

If this prescaling function is not used, the input frequency (Hz) will be displayed.

It is also possible to specify time (seconds) as the display value. Refer to *Display Unit* on page page 31 for details.

The relationship between display and input is determined by the following equation. Set the prescale value according to the unit to be displayed.

Displayed value =  $f \times \alpha$ 

- f: Input pulse frequency (number of pulses in 1 second)
- α: Prescale value

#### (1) Displaying Rotation Rate

Display unit	Prescale value (α)
rpm	1/N × 60
rps	1/N

N: Number of pulses per revolution

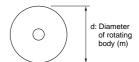
Example: To display the rate of rotation for a machine that outputs 5 pulses per revolution in the form  $\Box\Box.\Box$  rpm:

- 1. Set the decimal point position to 1 decimal places.
- 2. Using the formula, set the prescale value ( $\alpha$ ) to  $1/N \times 60 = 60/5 = 12$ .

#### (2) Displaying Speed

Display unit	Prescale value (α)
m/min	$\pi d \times 1/N \times 60$
m/s	$\pi d \times 1/N$

N: Number of pulses per revolution d: Diameter of rotating body (m) πd: Circumference (m)



• Observe the following points when setting a prescale value.

Set the set value to a value less than {Maximum countable value – Prescale value}.

Example: If the prescale value is 1.25 and the counting range is 0.000 to 999.999, set the set value to a value less than 998.749 (= 999.999 - 1.25).

If the set value is set to a value greater than this, output will not turn ON

Output will turn ON, however, if a present value overflow occurs (FFFFFF or FFFF).

Note: If the prescale value setting is incorrect, a counting error will occur. Check that the settings are correct before using this function.

#### Averaging Method (คืนนีะ) (Only for Tachometer Operation)

A simple average or moving average can be selected for the averaging. With the moving average method, the average of the measurement values is displayed each sampling cycle, in contrast to a simple average, with which the average of the set number of samples is displayed.

#### Number of Averaging Times (คืนนึก)★

Flickering display and output chattering can be prevented using average processing. Average processing can be set to one of four levels: no average processing, 2 times (i.e., the average of 2 measurement values), 4 times, 8 times, or 16 times.

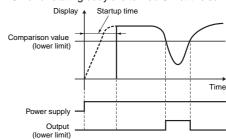
The measurement cycle will be equal to the sampling cycle multiplied by the average processing setting (i.e., the number of times). Average processing enables stable displays even for fluctuating input signals. Set the optimum number of times for the application.

#### Auto-zero Time (ฅ๘๒๘๓)

The display can be force-set to 0 if there is no pulse for a certain period of time. This time is called the auto-zero time. Set the auto-zero time to a time slightly longer than the estimated interval between input pulses. Accurate measurement is not possible if the auto-zero time is set to a time shorter than the input pulse cycle. Setting a time that is too long may also result in problems, such as a time-lag between rotation stopping and the alarm turning ON. The auto-zero time is not applied to pulse width measurements.

#### Startup Time (55mc)

To prevent undesired outputs resulting from unstable inputs immediately after the power supply is turned ON, it is possible to prohibit measurement for a set period of time, the startup time. It can also be used to stop measurements and disable outputs until the rotating body reaches the normal rate of rotation, after the power supply to the H7CX and rotating body are turned ON at the same time.



#### NPN/PNP Input Mode (ட்டிம்ம்)★

Select either NPN input (no-voltage input) or PNP input (voltage input) as the input format.

When using a two-wire sensor, select NPN input. The same setting is used for all external inputs.

For details on input connections, refer to *Input Connections* on page page 9.

#### Display Color (Lalr)

Set the color used for the measurement value.

	Control output OFF	Control output ON		
rEd	Red (fixed)			
Gen	Green (fixed)			
ŏrū	Orange	e (fixed)		
r-G *1	Measured value is displayed in red when both control outputs 1 and 2 are OFF.	Measured value is displayed in green when either control output 1 or control output 2 is ON.		
ũ-r *2	Measured value is displayed in green when both control outputs 1 and 2 are OFF.	Measured value is displayed in red when either control output 1 or control output 2 is ON.		
r-ă *3	Measured value is displayed in red when both control outputs 1 and 2 are OFF.	Measured value is displayed in orange when both control outputs 1 and 2 are OFF.		
ã-r *4	Measured value is displayed in orange when both control outputs 1 and 2 are OFF.	Measured value is displayed in red when both control outputs 1 and 2 are OFF.		
Ū-ā *5	Measured value is displayed in green when both control outputs 1 and 2 are OFF.	Measured value is displayed in orange when both control outputs 1 and 2 are OFF.		
ã-ũ *6	Measured value is displayed in orange when both control outputs 1 and 2 are OFF.	Measured value is displayed in green when both control outputs 1 and 2 are OFF.		

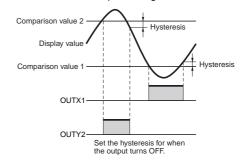
- \*1. If the tachometer output mode is set to AREA, however, the measured value is displayed in red when control output 1 is OFF and in green when control output 1 is ON.
- \*2. If the tachometer output mode is set to AREA, however, the measured value is displayed in green when control output 1 is OFF and in red when control output 1 is ON.
- \*3. If the tachometer output mode is set to AREA, however, the measured value is displayed in red when control output 1 is OFF and in orange when control output 1 is ON.
- \*4. If the tachometer output mode is set to AREA, however, the measured value is displayed in orange when control output 1 is OFF and in red when control output 1 is ON.
- \*5. If the tachometer output mode is set to AREA, however, the measured value is displayed in green when control output 1 is OFF and in orange when control output 1 is ON.
- \*6. If the tachometer output mode is set to AREA, however, the measured value is displayed in orange when control output 1 is OFF and in green when control output 1 is ON.

#### Peak/bottom Hold Enabled (dHL d)

This function records the peak and bottom (i.e., minimum) after counting starts (after turning ON the power supply or changing the configuration selection mode or function setting). The peak value is also held when the power supply is interrupted.

#### Output Hysteresis (서성5)

This setting can be used to prevent output chattering if the measurement value fluctuates slightly near the set value. The measurement value after prescaling is set.



#### Output OFF Delay ( FF d)

This function delays the timing for turning OFF comparative output by a certain time

The ON time can be held for the set time if the comparative result changes in a short time.

Operation will continue and outputs will not change when holding the value.

#### Set Value Upper Limit (PL -H)

Set the upper limit for the set value when it is set in run mode. The limit can be set to between 1 and 999999.

#### Output Allocation (å£5£)

When using an H7CX-AU□-N model as 2-stage counter, each output can be flexibly allocated to either stage 1 or 2.

The transistor output can be allocated to SV1 and the contact output to SV2 or vice verse, as in the following tables.

#### H7CX-AU-N/-AUD1-N

	Output 1	Output 2
ŏFF	Transistor (12-13)	Contact (3, 4, 5)
ŏn	Contact (3, 4, 5)	Transistor (12-13)

#### H7CX-AUSD1-N

	Output 1	Output 2
ŏFF	Transistor (12-13)	Transistor with diode (3, 4, 5)
ŏn	Transistor with diode (3, 4, 5)	Transistor (12-13)

#### Key Protect Level (# 남우년)

Set the key protect level.

Refer to Key Protect Level on page page 36.

# Pulse Cycle Measurement/Pulse Width Measurement ( $\mathit{ERL}_{m}$ )

Set the measurement mode to pulse cycle measurement or pulse width measurement.

With pulse cycle measurement, the number of pulse cycles that occur in 1 s is measured.

With pulse width measurement, the ON time for one pulse is measured.

An input OFF period of at least 20 ms is required for pulse width measurement.

If there is no input pulse during pulse width measurement, the previously measured value will be held.

#### Display Unit (いんと)

When pulse cycle measurement is used, set the display unit to Hz (hertz) or s (seconds).

#### Counting Interval (Lntu)

If the measurement speed is 10 kHz when pulse cycle measurement is used, set the measurement interval to 200 ms or Cont (10 ms min.).

# H7CX-A□-N

#### **Tachometer**

# ON Count Alarm Set Values for Outputs 1 and 2 (OUT1 and OUT2) ( $\delta \alpha$ lR and $\delta \alpha \delta R$ )

Set the ON count alarm values for the outputs 1 and 2.

The limit can be set to between  $\underline{0} \times 1000$  (0 times) and  $\underline{9999} \times 1000$  (9,999,000 times). Only the underlined values are set. The alarm will be disabled if 0 is set.

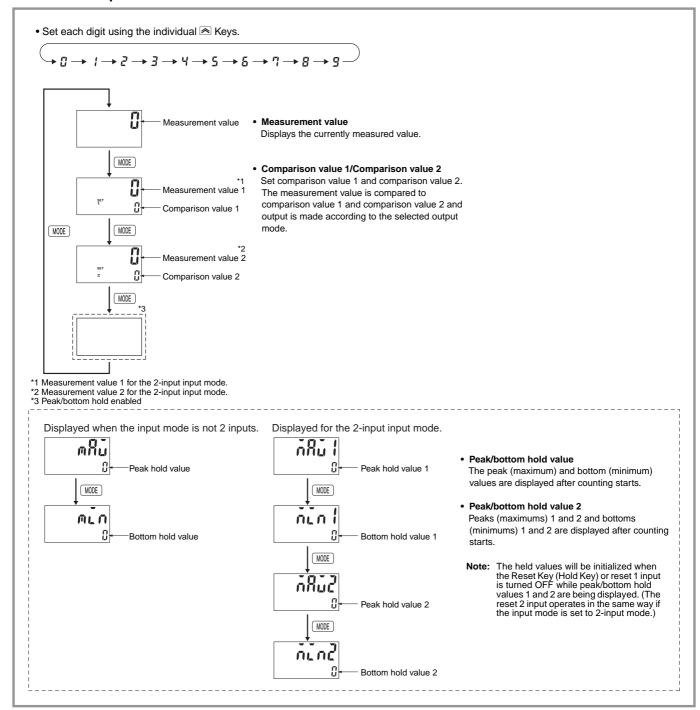
If the total ON count of instantaneous output 1 or 2 exceeds the alarm set value, £3 will be displayed on the Timer to indicate that the output ON count alarm value was exceeded. Refer to Self-diagnostic Function on page page 36 for information on the £3 display.

# ON Count Monitor Values for Outputs 1 and 2 (OUT1 and OUT2) (an IE and an EE)

The monitor value for output 1 or 2 is only displayed. It cannot be set. The output ON count will be 1,000 times the displayed value.

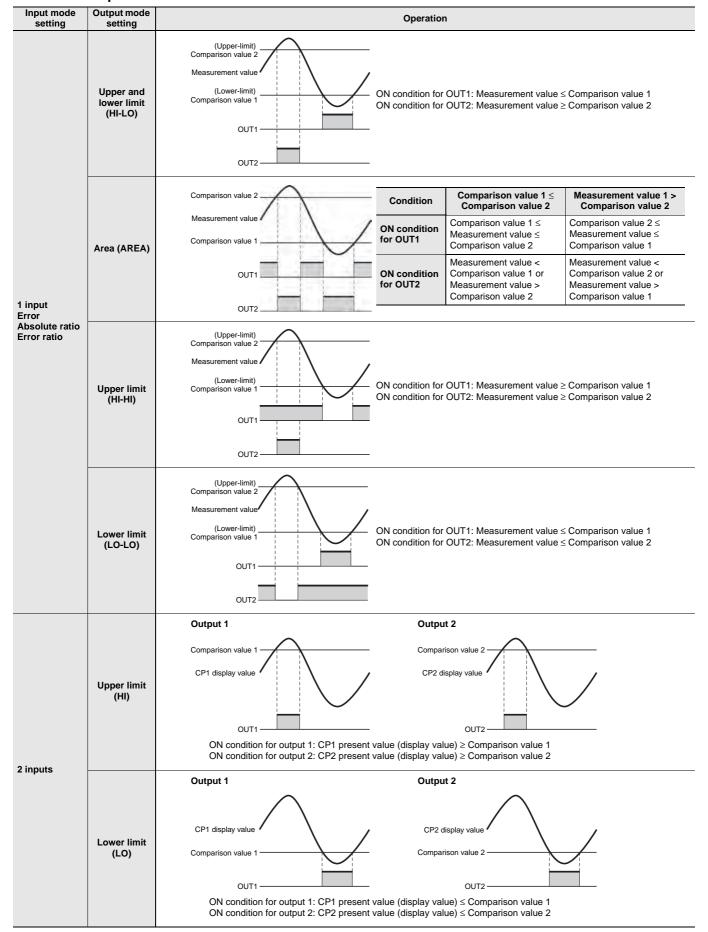
### **Operation in Run Mode**

#### **Tachometer Operation**



# **Output Mode Setting and Operation**

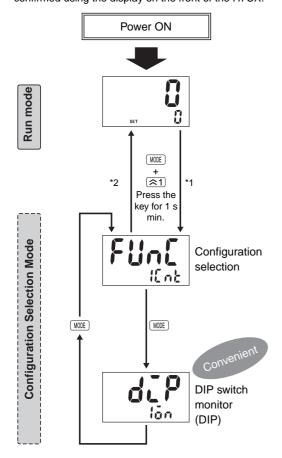
#### **Tachometer Operation**

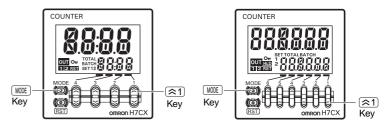


# Switching between Preset Counter, Total and Preset Counter, Batch Counter, Dual Counter, Twin Counter, and Tachometer Operation

Select which H7CX configuration is used (i.e., preset counter, total and preset counter, batch counter, dual counter, twin counter, or tachometer) in configuration selection mode.

The H7CX is also equipped with a DIP switch monitor function, a convenient function that enables the settings of the DIP switch pins to be confirmed using the display on the front of the H7CX.

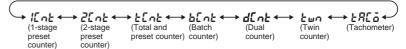




#### Note

To change the mode to configuration selection mode, hold down the <a>1</a> Key for 1 s min. with the <a>MODE</a> Key held down. The mode will not change if the <a>1</a> Key is pressed first.

Select the configuration using the Key.

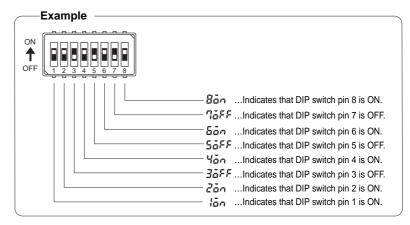


\*The configurations that can be selected depend on the model.

**Note:** By default, the H7CX is set to the 1-stage preset counter configuration. (Two-stage models are set to the 2-stage preset counter configuration.)

Confirm the status of DIP switch pins 1 to 8 using the Ney.

\*This display is possible only when DIP switch pin 1 (DIP switch settings enable/disable) is set to ON (enable).



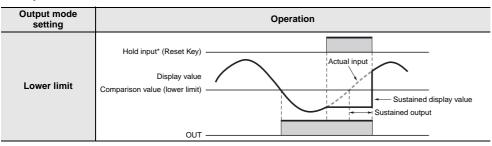
- \*1 When the mode is changed to configuration selection mode, the present value is reset, outputs turn OFF, and counting (measuring) stops.
- \*2 Setting changes made in configuration selection mode are enabled when the mode is changed to run mode. If the configuration is changed, the set value (or set value 1 and set value 2), comparison value 1 and comparison value 2 are initialized.

#### **Hold Function**

The measurement value (display value) and output are sustained while the hold input is ON.

Note: The output will maintain the current status when the hold key is pressed.

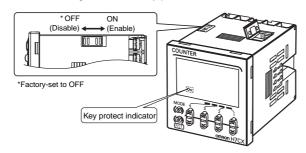
#### **Example:**



#### **Key Protect Level**

It is possible to prevent setting errors by prohibiting the use of certain operation keys by specifying the key protect level (KP-1 to KP-7) when the key-protect switch is set to ON.

The key protect level is set in the function setting mode. The key protect indicator is lit when the key-protect switch is ON.



	Description	Details			
Level		Changing modes*	Switching display during operation	Reset Key	Up/Down Keys
KP-1 (default setting)	MODE OF THE PROPERTY OF THE PR	Invalid	Valid	Valid	Valid
KP-2	MODE OMRON H7CX	Invalid	Valid	Invalid	Valid
KP-3	MODE OF THE STATE	Invalid Valid		Valid	Invalid
KP-4	MODE OF THE STATE	Invalid	Invalid Valid		Invalid
KP-5	MODE STATE OF THE	Invalid	Invalid Invalid		Invalid
KP-6	MODE STATE OF THE PARTY OF THE	Invalid	Invalid	Valid	Valid
KP-7	MODE OF THE STATE	Invalid	Invalid	Invalid	Valid

<sup>\*</sup> Changing mode to configuration selection mode or function setting mode.

#### **Self-diagnostic Function**

The following displays will appear if an error occurs.

Main display	Sub-display	Description	Output status	Correction method	Set value after reset
()*1*5	No change	Present value underflow*3	No change	Either press the Reset Key or turn ON reset input.	No change
FFFFF (FFFF)*1*5	No change	Present value overflow*4	No change	Either press the Reset Key or turn ON reset input.*6	No change
ΕΙ	Not lit	CPU error	OFF	Either press the Reset Key or reset the power supply.	No change
E2	Not lit	Memory error (RAM)	OFF	Turn ON the power again.	No change
£2	SUA	Memory error (EEPROM)*2	OFF	Reset Key	Factory setting
<i>E 3</i> *8	No change	Output Counter Overflow	No change	Reset Key*7	No change

- \*1. Displays for 4-digit models are given in parentheses.
- \*2. This includes times when the life of the EEPROM has expired.
- \*3. This occurs if the present value or total count value falls below –99999 (–999 for 4-digit models).
- \*4. This occurs in the following conditions if the present value (i.e., measurement value) exceeds 999999 (9999 for 4-digit models).
  - For Output Modes K-2, D, L, or H
  - Dual counter or tachometer operation is used.
- \*5. Display flashes.(1-second cycles)
- \*6. This does not apply when tachometer operation is used.

- \*7. This is displayed if the alarm value setting for either of the two outputs is exceeded if a model with two outputs is used. The total ON count will not be cleared by using the Reset Key.
- \*8. The normal display and £3 will appear alternately. When the Reset Key is pressed, £3 will not be displayed even if the alarm set value is exceeded. (Monitoring is possible, however, because the counter will continue without
  - (Monitoring is possible, nowever, because the counter will continue withou the output ON count being cleared.)

#### H7CX-R□-N Tachometer

- ullet Tachometer-only model (DIN 48  $\times$  48) for the H7CX (Supports display and alarm outputs for numbers of rotations, speed, and flow rate.)
- Socket design allows either flush or surface mounting.
- "-W" models added for control with two independent measurements.
- Operation in any of the four following modes is possible with the same Unit: Upper and lower limit, upper limit, lower limit, and area.
- Equipped with auto-zero time, average processing, and startup time functions.



# **Specifications**

# Ratings

	Classification	on Tachometer					
Item Model		H7CX-	H7CX-R11W□-N				
Input mode		1 input only			2 inputs only		
	Power supply voltage*1	100 to 240 VAC, 50/60 Hz     12 to 24 VDC or 24 VAC, 50/60 Hz					
Ratings	Operating volt- age fluctuation range	85% to 110% of rated supply voltage (90% to 110% at 12 to 24 VDC)					
	Power consump- tion	Approx. 9.4 VA at 100 to 240 VAC, Approx. 7.2 VA/4.7 W at 24 VAC/12 to 24 VDC, Approx. 3.7 W at 12 to 24 VDC					
Mounting me	thod	Flush mounting or surface mounting					
External con	nections	11-pin socket					
Degree of pro	otection	IEC IP66, UL508 Type 4 (indoors) for pan	el surface only and wh	nen Y92S-29 Waterpro			
Input signals		Count and hold			Count 1 and count 2		
Pulse measu	rement method	Tachometer mode (cycle measurement)	AMD-compatible mo measurement)	de (continuous	Tachometer mode (cycle measurement)		
Maximum co	unting speed	30 Hz 10 kHz	-		5 kHz		
Minimum inp	ut signal width		10 ms	1 ms			
Measuring ra	inges	0.01 Hz to 30.00Hz   0.01 Hz to 10 kHz	0.026 to 999999 s	0.003 to 999999 s	0.01 to 5k Hz		
Sampling cy	cle	200 ms min.	Continuous measure interval of 10 ms)	ement (minimum	200 ms min.		
Display refresh cycle		Input pulse of 5 Hz min.     Averaging not used: 200 ms     Averaging used: 200 multiplied by the averaging setting (ms)     Input pulse of less than 5 Hz     Using averaging: Two times the maximum input pulse cycle     Using averaging: Two times the maximum of the input pulse cycle multiplied by the averaging setting.					
Measuring ad	ccuracy	±0.1% FS ±1 digit max. (at 23 ±5°C)					
Output mode		HI-LO, AREA, HI-HI, LO-LO			HI-HI, LO-LO		
Auto-zero tin	ne	0.1 to 999.9 s (in Tachometer Mode)			1		
Startup time		0.0 to 99.9 s					
Averaging		Simple averaging/moving averaging selectable, Number of times: OFF, 2, 4, or 8 times					
Prescaling fu	ınction	0.001 to 99.999 (in Tachometer Mode)					
Decimal poin	t adjustment	Rightmost 3 digits					
Sensor waiti	ng time	290 ms max. (Control output is turned OFF and no input is accepted during sensor waiting time.)					
Input	$\begin{tabular}{l lllllllllllllllllllllllllllllllllll$						
	Hold input	Minimum input signal width: 20 ms					
External power supply		12 VDC (±10%), 100 mA * Refer to Safety Precautions (Common) on page page 52 for details.					
Control output		Contact output: 3 A at 250 VAC/30 VDC, resistive load (cos $\phi$ =1) Minimum applied load:10 mA at 5 VDC (failure level: P, reference value)					
Display*2		7-segment, negative transmissive LCD Character height Present value: 10 mm (red), comparison value: 6 mm (green)					
Digits		6 digits (0 to 999999)					
Memory back	•	EEPROM (overwrites: 100,000 times min.	•				
	mperature range	-10 to 55°C (-10 to 50°C if Counter/Tacho		side by side) (with no	icing or condensation)		
	perature range	−25 to 70°C (with no icing or condensation	n)				
	midity range	25% to 85%					
Case color		Black (N1.5)					
1 Do not use	a the output from an ir	overter as the nower supply. The ripple mus	t ha 20% maximum fo	or CC nower			

<sup>\*1.</sup> Do not use the output from an inverter as the power supply. The ripple must be 20% maximum for CC power.

<sup>\*2.</sup> The display is lit only when the power is ON. Nothing is displayed when power is OFF.

### **Characteristics**

		Lagarda I. ( a Egg VBQ) I i		
Insulation resistance		100 M $\Omega$ min. (at 500 VDC) between current-carrying terminal and exposed non-		
		current-carrying metal parts, and between non-continuous contacts		
		2,000 VAC, 50/60 Hz for 1 min between current-carrying metal parts and non-current-		
		carrying metal parts		
Dielectric strength		2,000 VAC (for 100 to 240 VAC), 50/60 Hz for 1 min between power supply and input		
Dielectric Sti	engtn	circuit (1,000 VAC for 24 VAC/12 to 24 VDC)		
		2,000 VAC 50/60 Hz for 1 min between control output, power supply, and input circuit		
		1,000 VAC, 50/60 Hz for 1 min between non-continuous contacts		
		3.0 kV (between power terminals) for 100 to 240 VAC, 1.0 kV for 24 VAC/12 to 24 VDC		
Impulse with	stand voltage	4.5 kV (between current-carrying terminal and exposed non-current-carrying metal		
•		parts) for 100 to 240 VAC, 1.5 kV for 24 VAC/12 to 24 VDC		
		±1.5 kV (between power terminals)		
Noise immui	nity	±600 V (between input terminals)		
		Square-wave noise by noise simulator (pulse width: 100 ns/1 μs, 1-ns rise)		
Static immui	nity	Destruction: 15 kV, Malfunction: 8 kV		
Vibration	Destruction	10 to 55 Hz with 0.75-mm single amplitude, each in three directions for 2 hours		
resistance	Malfunction	10 to 55 Hz with 0.35-mm single amplitude, each in three directions for 10 min		
Shock re-	Destruction	300m/s <sup>2</sup> each in three directions, three cycles		
sistance	Malfunction	100m/s <sup>2</sup> each in three directions, three cycles		
	•	Mechanical: 10,000,000 operations min.		
Life expectancy		Electrical: 100,000 operations min. (3 A at 250 VAC, resistive load, ambient		
		temperature condition: 23°C) *		
Weight		Approx. 110 g (Tachometer only)		

<sup>\*</sup> See Life-test Curve (Reference Values) on the right.

# **Applicable Standards**

Applie	ouble Glarida us					
Approved	cULus (or cURus): UL508/CSA C22.2 No. 14*					
safety	Conforms to EN 61010-1 (IEC 61010-1): Pollution degree 2/overvoltage category II, B300 PILOT DUTY,					
standards	1/4 HP 120 VAC, 1/3 HP, 240 VAC	, 3-A resistive lo	ad			
	(EMI)	EN61326				
	Emission Enclosure:	EN55011 Gro	up 1 classA			
	Emission AC mains:	EN55011 Gro	up 1 classA			
	(EMS)	EN61326				
	Immunity ESD:	EN61000-4-2:	4 kV contact discharge (level 2);			
			8 kV air discharge (level 3)			
	Immunity RF-interference:	EN61000-4-3:	10 V/m (Amplitude-modulated, 80 MHz to 1 GHz)			
EMC			(level 3);			
			10 V/m (Pulse-modulated, 900 MHz ±5 MHz) (level 3)			
	Immunity Conducted Disturbance:	EN61000-4-6:	10 V (0.15 to 80 MHz) (level 3)			
	Immunity Burst:	EN61000-4-4:	2 kV power-line (level 3);			
			1 kV I/O signal-line (level 4)			
	Immunity Surge:	EN61000-4-5:	1 kV line to lines (power and output lines) (level 2);			
			2 kV line to ground (power and output lines) (level 3)			
	Immunity Voltage Dip/Interruption:	EN61000-4-11	: 0.5 cycle, 100% (rated voltage)			

<sup>\*</sup> The following safety standards apply to the H7CX-R11□. cUL (Listing): Applicable when an OMRON P2CF(-E) Socket is used. cUR (Recognition): Applicable when any other socket is used.

#### I/O Functions

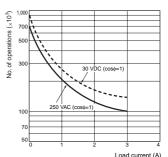
Inputs	Count, count 1, count 2	Reads counting signals.
	Hold	Holds the measurement value and outputs.     The hold indicator is lit during hold.*
Outputs OUT		Outputs signals according to the specified output mode when a comparison value is reached.

<sup>\*</sup> Refer to page page 50 for details on the hold function.

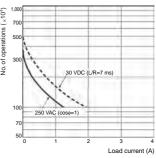
• The following table shows the delay from when the reset signal is input until the output is turned OFF. (Reference values)

Minimum reset signal width	Output delay time
1 ms	0.8 to 1.2 ms
20 ms	15 to 25 ms

#### Life-test Curve (Reference Values) Resistive Load



#### **Inductive Load**

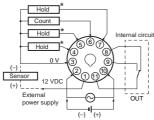


A current of 0.15 A max. can be switched at 125 VDC (cose=1) (Life expectancy: 100,000 operations)
A current of 0.1 A max. can be switched if L/R=7 ms.
(Life expectancy: 100,000 operations)

# **Connections**

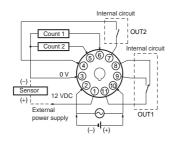
### **Terminal Arrangement**

#### H7CX-R11-N H7CX-R11D1-N



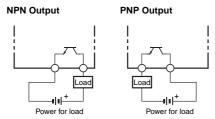
\* The hold function is the same whichever terminal is connected. Terminals are not connected internally, and so do not use them for cross-over wiring.

#### H7CX-R11W-N H7CX-R11WD1-N

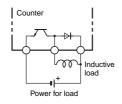


#### **Transistor Output**

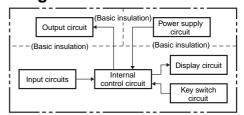
• The transistor output of the H7CX is isolated from the internal circuitry by a photocoupler, so the transistor output can be used as both NPN and PNP output.



 The diode connected to the collector of the output transistor is used to absorb inverted voltage that is generated when an inductive load is connected to the H7CX.

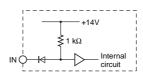


# **Block Diagram**

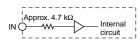


# Input Circuits Count and Hold Inputs

# No-voltage Inputs (NPN Inputs)



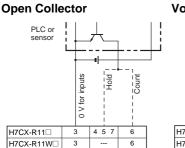
# Voltage Inputs (PNP Inputs)

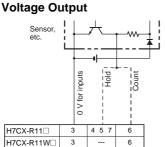


# **Input Connections**

The inputs of the H7CX-R are no-voltage (short-circuit or open) inputs or voltage inputs. They are set for use as voltage inputs at the time of delivery.

#### **No-voltage Inputs (NPN Inputs)**

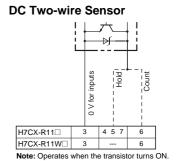




Note: Operates when the transistor turns ON

# 0 V for inputs H7CX-R11□ H7CX-R11W

**Contact Input** 



Note: Operates when the transistor turns ON

No-contact input	$\label{eq:short-circuit level (Transistor ON)} \begin{tabular}{ll} \bullet & Residual voltage: 3 V max. \\ \bullet & Impedance when ON: 1 k\Omega max. \\ & (The leakage current is approx. 12 mA when the impedance is 0 \Omega.)$	
	Open level (Transistor OFF) • Impedance when OFF: 100 $k\Omega$ min.	
Contact in- put	Use contacts which can adequately switch 5 mA at 10 V.	

No-voltage Input Signal Levels

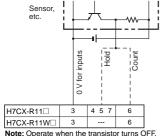
Note: The DC voltage must be 30 VDC max.

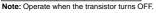
#### Applicable Two-wire Sensor

- Leakage current: 1.5 mA max.
- Switching capacity: 5 mA min.
- Residual voltage: 3 VDC max.
- Operating voltage: 10 VDC

# **Voltage Inputs (PNP Inputs)**

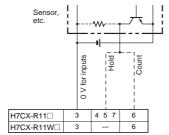
# **No-contact Input (NPN Transistor)**





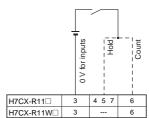
Voltage Input Signal Levels High level (Input ON): 4.5 to 30 VDC Low level (Input OFF): 0 to 2 VDC

**No-contact Input (PNP Transistor)** 



Note: Operate when the transistor turns ON

#### **Contact Input**



Note: Operate when the contact turns ON.

Note: 1	The DC voltage must be 30 VDC max.
NOLE. I.	THE DC VOILAGE HIUST DE 30 VDC HIAX.

**2.** Input resistance: Approx. 4.7 k $\Omega$ 

# **Nomenclature**

#### **Display Section**

- 1. Hold Indicator (orange) (Lit when the hold input or hold key is ON.)
- 2. Key Protect Indicator (orange) Lit when the key protect switch is ON
- 3. Control Output Indicator (orange)

OUT (1-output models) OUT 1 2 (2-output models)

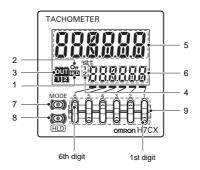
- 4. Comparison Value 1, 2 Stage Indicator
- 5. Present Value (Main Display) Character height: 10 mm (red)
- 6. Comparison Value (Sub-display) Character height: 6 mm (green)

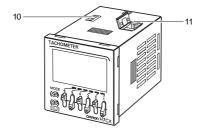


Character Size for Sub-display









#### **Operation Keys**

#### 7. Mode Key

(Used to switch mode and setting items.)

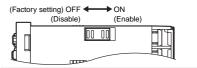
#### 8. Hold Key

(Used to sustain the measurement value and output.)

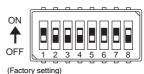
#### 9. Up Keys 1 to 6

#### **Switches**

#### 10. Key-protect Switch



#### 11. DIP Switch

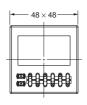


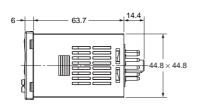
(Unit: mm)

# **Dimensions Tachometers**

# **Dimensions without Flush Mounting Adapter** H7CX-R□-N

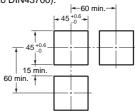




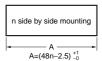


#### **Panel Cutouts**

Panel cutouts are as shown below (according to DIN43700).

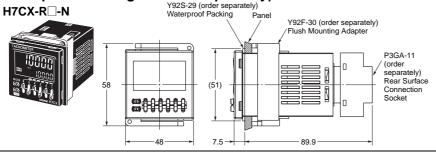


- The mounting panel thickness should be 1 to 5 mm.
- The mounting panel thickness should be 1 to 5 mm. To allow easier operation, it is recommended that Adapters be mounted so that the gap between sides with hooks is at least 15 mm (i.e., with the panel cutouts separated by at least 60 mm). It is possible to mount counters side by side, but only in the direction without the hooks. If Counters/Tachometers are mounted side by side, however, water resistance will be lost.

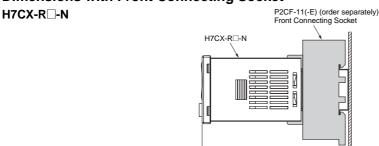


With Y92A-48F1 attached.  $A=\{48n-2.5+(n-1)\times 4\}_{-0}^{+1}$ With Y92A-48 attached.  $A=(51n-5.5)^{+1}_{-0}$ 

# **Dimensions with Flush Mounting Adapter (Adapter and** Waterproof Packing Ordered Separately)



#### **Dimensions with Front Connecting Socket**



100.9 103.2 \* These dimensions vary with the kind of DIN track (reference value).

# **Accessories (Order Separately)**

Note: Depending on the operating environment, the condition of resin or rubber products may deteriorate, or they may shrink or become harder. Therefore, it is recommended that resin products be replaced regularly.

#### Soft Cover Y92A-48F1



#### Protecting the Timer in Environments Subject to Oil

The H7CX's panel surface is water-resistive (conforming to IP□6, UL Type 4X) and so even if drops of water penetrate the gaps between the keys, there will be no adverse effect on internal circuits. If, however, there is a possibility of oil being present on the operator's hands, use the Soft Cover. The Soft Cover ensures protection equivalent to IP54 against oil. Do not, however, use the H7CX in locations where it would come in direct contact with oil.

#### Hard Cover Y92A-48



# Flush Mounting Adapter

Y92F-30

Order a Flush Mounting Adapter separately if the product is to be flush-mounted.



# Waterproof Packing Y92S-29



previously made for a DIN 72 × 72 mm

device (panel cutout: 68 × 68 mm).

Use this Adapter to install the

Counter/Tachometer in a cutout

Y92F-45



Order the Waterproof Packing separately if it is lost or damaged. The Waterproof Packing can be used to achieve protection equivalent to IP66.

(The Waterproof Packing will deteriorate, harden, and shrink depending on the application environment. To ensure maintaining the NEMA4 waterproof level, periodically replace the Waterproof Packing. The periodic replacement period will depend on the application environment. You must confirm the proper replacement period. Use 1 year or less as a guideline. If the Waterproof Packing is not replaced periodically, the waterproof level will not be maintained.) It is not necessary to mount the Waterproof Packing if waterproof construction is not required.

#### **Connection Sockets**

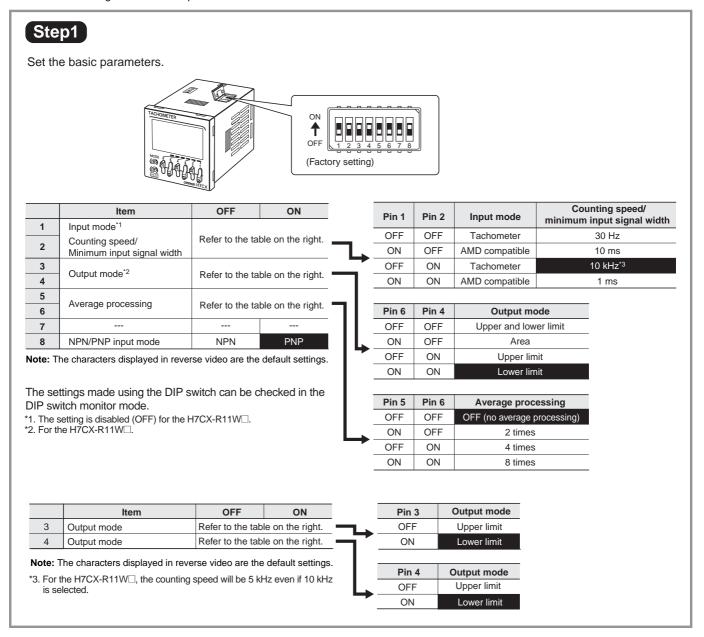
Refer to Connection Sockets on page page 13 for details.

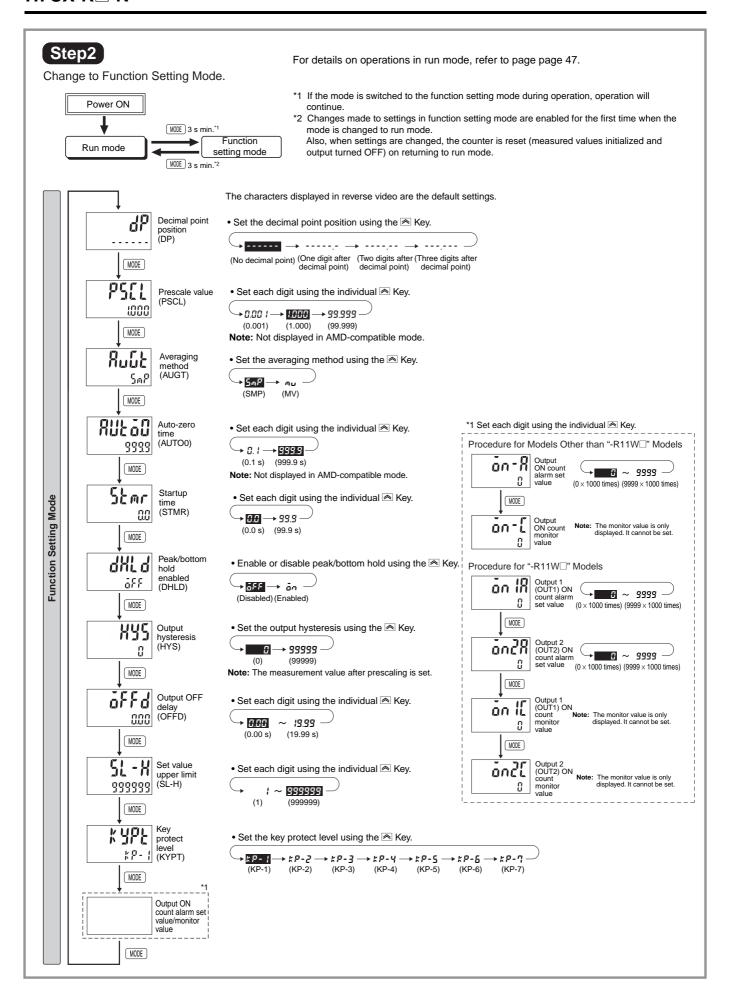
### **Optional Products for Track Mounting**

Refer to Optional Products for Track Mounting on page page 14 for details.

# **Operating Procedures**

Parameters must be set using both the DIP switch and the operation keys on the front panel. Refer to the following for the detailed procedure.





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# **Explanation of Functions**

#### **Basic Functions**

#### **Input Mode**

The mode can be switched between tachometer mode and AMD-compatible mode.

#### **Tachometer Mode**

Use this mode to measure the pulse frequency (Hz).

#### **AMD-compatible Mode**

Use this mode to measure the pulse cycle (s).



#### **Counting Speed**

Set the maximum counting speed (30 Hz/10 kHz) for input. If contacts are used for input signals, set the counting speed to 30 Hz. Processing to eliminate chattering is performed for this setting.

#### **Output Mode**

Set the output method for control output based on the comparison

Upper and lower limit (HI-LO), area (AREA), upper limit (HI), and lower limit (LO) can be set. For the H7CX-RW□, the upper limit (HI-HI) and lower limit (LO-LO) can be set. (For details on the operation of the output modes, refer to *Output Mode Settings* on page page 49.)

#### Averaging Method (គឺធនិង)

Simple averaging or a moving average can be selected for the averaging method.

With a moving average, the average measurement value is displayed every sampling cycle or pulse cycle, in contrast to simple averaging, for which the average value is displayed for the set number of samples.

#### **Number of Averaging Times**

Flickering display and output chattering can be prevented using average processing. Average processing can be set to one of four levels: no average processing, 2 times (i.e., the average of 2 measurement values), 4 times, or 8 times.

For a measurement frequency of 5 Hz or higher using a tachometer, the average will be equal to the sampling cycle (200 ms) multiplied by the averaging setting (i.e., the number of times).

For less than 5 Hz, the frequency will be measured when the input pulse comes. Average processing produces a stable display even for fluctuating input signals. Set the optimum number of times for the application.

If AMD-compatible mode is used, the measurement cycle will be measured when the input pulse is received. The output will change, however, when the comparison value is exceeded even if averaging is enabled.

#### **NPN/PNP Input Mode**

Select either NPN input (no-voltage input) or PNP input (voltage input) as the input format. When using a two-wire sensor, select NPN input

The same setting is used for all external inputs.

For details on input connections, refer to *Input Connections* on page page 40.

#### **Advanced Functions**

#### Decimal Point Position (dp)

Decide the decimal point position for the measurement value and comparison value.

#### Prescale Value (PSCI)

It is possible to display the rate of rotation or the speed of a device or machine to which the H7CX is mounted by converting input pulses to a desired unit.

If the default prescaling value (1,000) is used, the input frequency (Hz) will be displayed.

The relationship between display and input is determined by the following equation. Set the prescale value according to the unit to be displayed.

Displayed value =  $f \times \alpha$ 

f: Input pulse frequency (number of pulses in 1 second)

α: Prescale value

#### (1) Displaying Rotation Rate

Display unit	Prescale value (α)		
rpm	1/N × 60		
rps	1/N		

N: Number of pulses per revolution

Example: In order to display the rate of rotation for a machine that outputs 5 pulses per revolution in the form  $\Box\Box.\Box$  rpm:

- 1. Set the decimal point position to 1 decimal places.
- 2. Using the formula, set the prescale value ( $\alpha$ ) to  $1/N \times 60 = 60/5 = 12$ .

#### (2) Displaying Speed

	Display unit	Prescale value (α)		
m/min		$\pi d \times 1/N \times 60$		
m/s		$\pi d \times 1/N$		

N: Number of pulses per revolution

d: Diameter of rotating body (m)

 $\pi d$ : Circumference (m)



 Observe the following points when setting a prescale value.

Set the set value to a value less than {Maximum countable value – Prescale value}.

Example: If the prescale value is 1.25 and the counting range is 0.000 to 999.999, set the set value to a value less than 998.749 (= 999.999 - 1.25).

If the set value is set to a value greater than this, output will not turn ON.

Note: If the prescale value setting is incorrect, a counting error will occur. Check that the settings are correct before using this function.

# Auto-zero Time (คืนะอันิ)

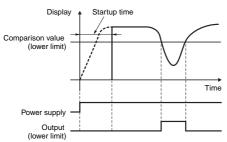
It is possible to make the settings so that the frequency will be forceset to 0 if there is no pulse for a specified period of time. This time is called the auto-zero time.

Note: Set the auto-zero time to a time slightly longer than the estimated interval between input pulses. It will not be possible to make accurate measurements if the auto-zero time is set to a time shorter than the input pulse cycle. Setting a time that is too long may also result in problems, such as a time-lag between rotation stopping and the alarm turning ON.

#### Startup Time (5kmr)

In order to prevent undesired output resulting from unstable input immediately after the power supply is turned ON, measurement can be prohibited for a set time at startup.

It can also be used to stop measurement and disable output until the rotating body reaches the normal rate of rotation, after the power supply to the H7CX and rotating body are turned ON at the same time.



#### Peak/bottom Hold Enabled (dHL d)

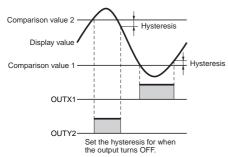
This function records the peak and bottom (i.e., minimum) values after counting starts (after turning ON the power supply or changing the configuration selection mode or function setting).

The peak value is also held when the power supply is interrupted.

#### Output Hysteresis (445)

This setting can be used to prevent output chattering if the measurement value fluctuates slightly near the set value.

In Thachometer Mode, the measurement value after prescaling is set.



#### Output OFF Delay (aFFd)

This function delays the timing for turning OFF comparative output by a certain time.

The ON time can be held for the set time if the comparative result changes in a short time.

Operation will continue and outputs will not change while holding the value.

#### Set Value Upper Limit (54 - 4)

Set the upper limit for the set value when it is set in run mode.

#### Key Protect Level (남우남)

Set the key protect level.

Refer to Key Protect Level on page page 48.

#### Output ON Count Alarm Set Value (\$\int\_0^2 - \beta\$)

Set the alarm value for the output ON count.

The limit can be set to between  $\underline{0} \times 1000$  (0 times) and  $\underline{9999} \times 1000$ (9,999,000 times). Only the underlined values are set. The alarm will be disabled if 0 is set.

If the total ON count of the output exceeds the alarm set value, £3 will be displayed on the Timer to indicate that the output ON count alarm value was exceeded. Refer to Self-diagnostic Function on page page 48 for information on the £3 display.

#### ON Count Alarm Set Values for Outputs 1 and 2 (OUT1 and OUT2) (an IR and and R)

Set the ON count alarm values for the outputs 1 and 2.

The limit can be set to between  $\underline{0} \times 1000$  (0 times) and  $\underline{9999} \times 1000$ (9,999,000 times). Only the underlined values are set. The alarm will be disabled if 0 is set.

If the total ON count of instantaneous output 1 or 2 exceeds the alarm set value, £3 will be displayed on the Timer to indicate that the output ON count alarm value was exceeded. Refer to Self-diagnostic *Function* on page page 48 for information on the £3 display.

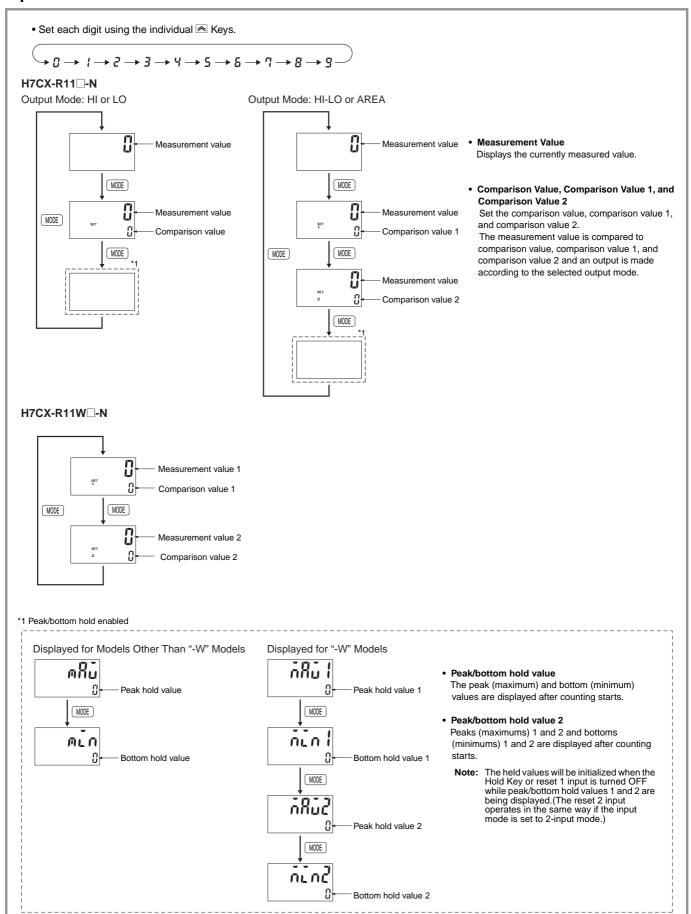
#### Output ON Count Monitor Value (50-5)

The monitor value is only displayed. It cannot be set. The output ON count will be 1,000 times the displayed value.

#### ON Count Monitor Values for Outputs 1 and 2 (OUT1 and OUT2) (on IE and on EE)

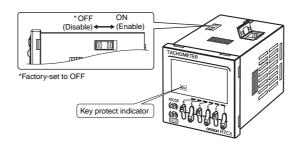
The monitor value for output 1 or 2 is only displayed. It cannot be set. The output ON count will be 1,000 times the displayed value.

### **Operation in Run Mode**



### **Key Protect Level**

When the key-protect switch is set to ON, it is possible to prevent setting errors by prohibiting the use of certain operation keys by specifying the key protect level (KP-1 to KP-7). The key protect level is set in the function setting mode. The key protect indicator is lit when the key-protect switch is ON.



		Details				
Level	Meaning	Changing mode*	Switching display during operation	Hold Key	Up Key	
KP-1 (default setting)	MODE STATE OF THE PARTY OF THE	Invalid	Valid	Valid	Valid	
KP-2	MODE OF THE PROPERTY OF THE PR	Invalid	Valid	Invalid	Valid	
КР-3	MODE OF THE PROPERTY OF THE PR	Invalid	Valid	Valid	Invalid	
KP-4	MODE OF THE PARTY	Invalid	Valid	Invalid	Invalid	
KP-5	MODE OF THE PARTY	Invalid	Invalid	Invalid	Invalid	
KP-6	MODE TO THE TOTAL OF THE TOTAL	Invalid	Invalid	Valid	Valid	
KP-7	MODE TO THE PART OF THE PART O	Invalid	Invalid	Invalid	Valid	

<sup>\*</sup> Changing mode to DIP switch monitor mode or function setting mode.

# **Self-diagnostic Function**

The following displays will appear if an error occurs.

Main display	Sub-display	Error	Output status	Correction method	Set value after reset
FFFFFF *3	No change	Measurement value overflow*2	No change	Measurement value ≤ 999999	No change
E I	Not lit	CPU	OFF	Either press the hold key or reset the power supply.	No change
£2	Not lit	Memory error (RAM)	OFF	Turn ON the power again.	No change
E2	SUA	Memory error (EEP)*1	OFF	Hold Key	Factory setting
E3 *4	No change	Output Counter Overflow	No change	Hold Key	No change

<sup>\*1.</sup> This includes times when the life of the EEPROM has expired.

<sup>\*2.</sup> Occurs when the measurement value reaches 999,999.

<sup>\*3.</sup> Display flashes (1-second cycles).

<sup>\*4.</sup> The normal display and £3 will appear alternately.

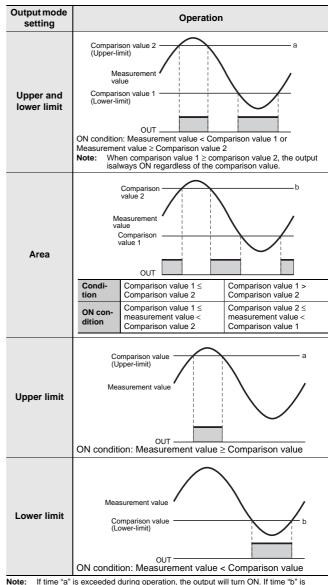
When the Hold Key is pressed, £3 will not be displayed even if the alarm set value is exceeded. (Monitoring is possible, however, because the counter will continue without clearing the output ON count.)

# **Output Mode Settings**

#### Models Other Than H7CX-R11W□ in Tachometer Mode

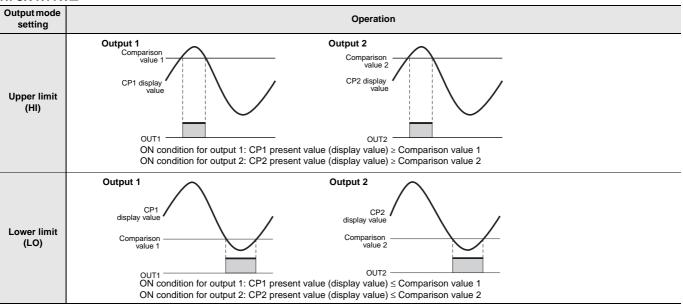
# Output mode Operation setting Comparison value 2 (Upper-limit) Upper and Comparison value ( (Lower-limit) lower limit ON condition: Measurement value ≤ Comparison value 1 or Measurement value ≥ Comparison value 2 Note: When comparison value 1 ≥ Comparison value 2, the output isalways ON regardless of the comparison value. Area OUT Comparison value 1 ≤ Comparison value 1 tion Comparison value 2 Comparison value 2 Comparison value 1 ≤ Comparison value 2 ≤ measurement value ≤ measurement value ≤ dition Comparison value 2 Comparison value 1 Comparison value (Upper-limit) Measurement value **Upper limit** OUT ON condition: Measurement value ≥ Comparison value Measurement value Lower limit OUT ON condition: Measurement value ≤ Comparison value

# Models Other Than H7CX-R11W $\square$ in AMD-compatible Mode



Note: If time "a" is exceeded during operation, the output will turn ON. If time "b" is exceeded during operation, the output will turn OFF. (If average processing is enabled, the output operation will be performed when the time is exceeded once.)

#### H7CX-R11W



#### Precautions for the H7CX-R

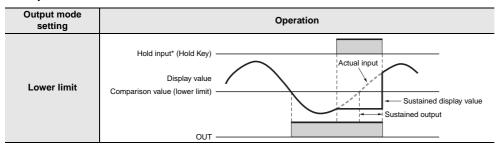
In upper and lower limit output mode, if the comparison value setting is such that comparison value 1 ≥ comparison value 2, the output will always be ON.

#### **Hold Function**

The measurement value (display value) and output are sustained while the hold input is ON.

Note: The output will maintain the current status when the hold key is pressed.

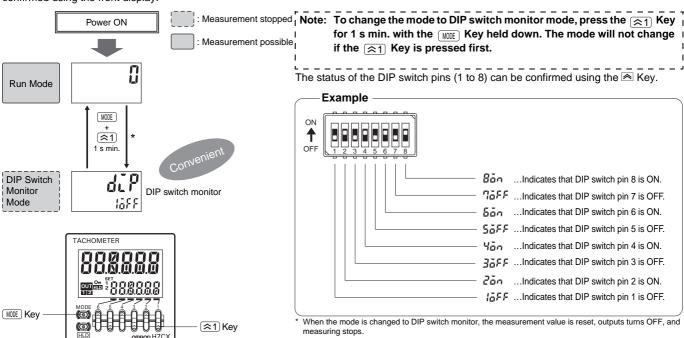
#### **Example:**



<sup>\*</sup> The H7CX-R11W□-N does not have a hold input

### **Operation in DIP Switch Monitor Mode**

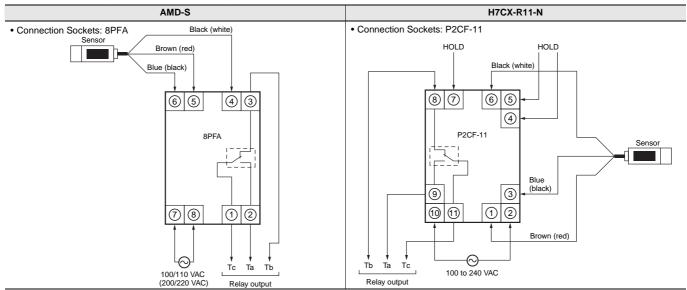
The H7CX-R is also equipped with a DIP switch monitor function, a convenient function that enables the settings of the DIP switch pins to be confirmed using the front display.



# Precautions on Replacing the AMD-S

The H7CX-R11-N is the recommended model for replacing the AMD-S-series Motion Detector. Refer to the following precautions before replacing the AMD-S.

#### **Terminal Arrangement and Wiring Connections**



Note: 1. Wiring must be changed from an 8-pin socket to an 11-pin socket.

- 2. Take into consideration the length of the wires and the terminal numbers.
- 3. Order the P2CF-11Connecting Socket separately.

#### **Setting Procedure**

Perform the following settings to achieve the functions of the AMD-S using the H7CX-R11-N.

#### **DIP Switch Settings**

Model		H7CX-R11-N			
Item	AMD-S	AMD-S  DIP switch pin status *			
Measuring ranges	0.01 to 0.1 s (AMD-S□1), 0.1 to 1 s (AMD- S□2), 1 to 10 s (AMD-S□3)	Set DIP switch pin 1 to ON for AMD-compatible mode.  Pin 1 Pin 2 Input mode Minim pay signal with ON OFF AMD compatible 10 ms ON ON AMD compatible 1 ms	1 ms 10 ms		
Output	Rotation increase detection (AMD-SU□)	ON	Lower limit		
mode	Rotation decrease detection (AMD-SL□)	ON 0FF 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	Upper limit		
Average processing	None	ON	OFF		
Input mode	Voltage Input	ON	PNP		

Note: The characters displayed in reverse video are the default settings.

#### **Operation Key Settings**

Model		H7CX-R11-N			
Item	AMD-S	Parameter s	Setting range	Set value	
Startup time	Fixed (0.1 to 10 s)	SEMF (STMR)	0.0 s) (99.9 s)	0.0	

Note: The characters displayed in reverse video are the default settings.

#### **Characteristics**

Model Item	AMD-S	H7CX-R11-N		
Supply voltage	-100 to 110 VAC -200 to 220 VAC	-100 to 240 VAC		
Input method	Voltage input (high: 4 to 14 V, low: 0 to 1 V)	No-voltage input/voltage input (high: 4.5 to 30 V, low: 0 to 2 V)		
External pow- er supply	12 VDC ±1 V, 12 mA	12 VDC (±10%), 100 mA		
Relay output	5 A at 200 VAC (resistive load)	3 A at 250 VAC/30 VDC (resistive load)		
Output mode	Rotation increase (AMD-SU□) Rotation decrease (AMD-SL□)	HI-LO, AREA, HI-HI, LO-LO (Set using DIP switch.)		
Setting meth- od	Input pulse interval (s)	Input pulse interval (s) *		
Detection rota- tion rate range	6 to 6,000 rpm (for 1 pulse/rotation)	0.00006 to 20,000 rpm * (for 1 pulse/rotation)		
Startup time	Always from 0.1 to 10 s (Always 10 s if not specified.)	Setting range: 0.0 to 99.9 s		
Life expectan- cy	Output relay electrical operations of 500,000 min.	Output relay electrical operations of 100,000 min.		
Memory back- up	None	EEPROM (overwrites: 100,000 times min.)		

<sup>\*</sup> Refer to page page 43 for information on DIP switch settings.

# Safety Precautions for All H7CX Series (Common)

#### **⚠** CAUTION

Do not allow pieces of metal, wire clippings, or fine metallic shavings or fillings from installation to enter the product. Doing so may occasionally result in electric shock, fire, or malfunction.



Minor injury due to explosion may occasionally occur. Do not use the Counter where subject to flammable or explosive gas.



Fire may occasionally occur. Tighten the terminal screws to the rated torque.

H7CX terminals: 6.55 to 7.97 lb-in (0.74 to 0.90 N·m) P2CF Socket terminals: 4.4 lb-in (0.5 N·m)



Minor injury due to electric shock may occasionally occur. Do not touch any of the terminals while power is being supplied. Be sure to mount the terminal cover after wiring.



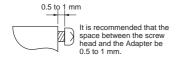
The life expectancy of the output relay varies considerably according to its usage. Use the output relay within its rated load and electrical life expectancy. If the output relay is used beyond its life expectancy, its contacts may become fused or there may be a risk of fire. Also, be sure that the load current does not exceed the rated load current and when using a heater, be sure to use a thermal switch in the load circuit.

Minor electric shock, fire, or malfunction may occasionally occur. Do not disassemble, modify, or repair the Counter or touch internal components.



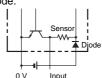
#### **Precautions for Safe Use**

 The panel surface of the H7CX-A/-R is water-resistant (conforming to NEMA4, IP66, UL Type 4X (Indoor Use Only). To protect the internal circuits from water penetration through the space between the H7CX and operating panel, waterproof packing is included. Attach the Y92F-30 Adapter with sufficient pressure with the reinforcing screws so that water does not penetrate the panel.



- When mounting the Counter to a panel, tighten the two mounting screws alternately, a little at a time, so as to keep them at an equal tightness. If the panel screws are tightened unequally, water may enter the panel.
- Store the Counter at the specified temperature. If the Counter has been stored at a temperature of less than
  - $-10^{\circ}\text{C},$  allow the Counter to stand at room temperature for at least 3 hours before use.
- Mounting the Counter side-by-side may reduce the life expectancies of internal components.
- Use the Counter within the specified ranges for the ambient operating temperature and humidity.
- · Do not use in the following locations:
  - Locations subject to sudden or extreme changes in temperature.
  - · Locations where high humidity may result in condensation.
- Do not use the Counter outside of the rated ranges for vibration, shock, water exposure, and oil exposure.
- Do not use this Counter in dusty environments, in locations where corrosive gasses are present, or in locations subject to direct sunlight.
- Install the Counter well away from any sources of static electricity, such as pipes transporting molding materials, powders, or liquids.

- Internal elements may be destroyed if a voltage outside the rated voltage range is applied.
- Be sure that polarity is correct when wiring the terminals.
- Separate the Counter from sources of noise, such as devices with input signals from power lines carrying noise, and wiring for I/O signals.
- Do not connect more than two crimp terminals to the same terminal.
- Up to two wires of the same size and type can be inserted into a single terminals.
- Use the specified wires for wiring. Applicable Wires: AWG 18 to AWG 22, solid or twisted, copper
- Install a switch or circuit breaker that allows the operator to immediately turn OFF the power, and label it to clearly indicate its function
- When the Counter is operated with no-voltage input (NPN input), approximately 14 V is output from the input terminals. Use a sensor that contains a diode.



- Use a switch, relay, or other contact so that the rated power supply voltage will be reached within 0.1 seconds. If the power supply voltage is not reached quickly enough, the Counter may malfunction or outputs may be unstable.
- Use a switch, relay, or other contact to turn the power supply OFF instantaneously. Outputs may malfunction and memory errors may occur if the power supply voltage is decreased gradually.
- When changing the set value during operation, because the H7CX uses a constant read-in system, output will turn ON if the set value is equal to the present value.
- When changing the comparison value during operation, because the H7CX uses a constant read-in system, the output status will change if the comparison value is changed to a value on the other side of the present value.
- If the set value and present value are both 0, the output will turn ON for the default setting. The output will turn OFF during a reset operation.
- When the power is turned ON using the factory settings, the output will turn ON after 999.9 s if no pulses are received as count input.
- Do not use organic solvents (such as paint thinners or benzine), strong alkali, or strong acids. They will damage the external finish.
- Confirm that indications are working normally, including the backlight LED, and LCD. The indicator LEDs, LCD, and resin parts may deteriorate more quickly depending on the application environment, preventing normal indications. Periodic inspection and replacement are required.
- The waterproof packing may deteriorate, shrink, or harden depending on the application environment. Periodic inspection and replacement are required.

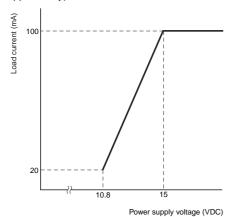
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#### **Precautions for Correct Use**

- H7CX models with a 12 to 24-VDC power supply use a transformer-free power supply method in which the power supply terminals are not isolated from the signal input terminals. If a nonisolating DC power supply is used, unwanted current paths may occasionally burn or destroy internal components depending on the wiring. Always check the wiring sufficiently before use.
- An inrush current of approx. 10 A will flow for a short time when the power supply is turned ON. If the capacity of the power supply is not sufficient, the Counter may not start. Be sure to use a power supply with sufficient capacity.
- Maintain voltage fluctuations in the power supply within the specified operating voltage range.
- When turning the power ON and OFF, input signal reception is possible, unstable, or impossible as shown in the diagram below.

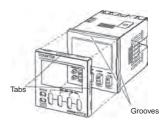
Power ON supply OFF						
	200 ms	0 to 9	0 ms 5	ms	0 to 1 s	
Input	Impossible	Unstable	Possible		Unstable	Impossible

- Inrush current generated by turning ON or OFF the power supply may deteriorate contacts on the power supply circuit. Turn ON or OFF to a device with the rated current of more than 10 A.
- The capacity of the external power supply is 100 mA at 12 V. When using a 24 VAC/12 to 24 VDC power supply, reduce the load with the power supply voltage, as shown in the following diagram (DC power supplies only).



- If the prescale value setting is incorrect, a counting error will occur.
   Check that the settings are correct before using this function.
- Make sure that all settings are appropriate for the application.
   Unexpected operation resulting in property damage or accidents may occur if the settings are not appropriate.
- Do not leave the Counter for long periods at a high temperature with output current in the ON state. Doing so may result in the premature deterioration of internal components (e.g., electrolytic capacitors).
- EEPROM is used as backup memory when the power is interrupted. The write life of the EEPROM is 100,000 writes. The EEPROM is written at the following times:
  - When the power supply is turned OFF
  - When switching from Configuration Selection Mode or Function Setting Mode to Run Mode
- Dispose of the product according to local ordinances as they apply.

- Attach the front panel when using the Counter. The tabs in the middle of each of four sides secure the front panel to the main body. To remove the panel, widen the four tabs and pull the panel toward you.
  - To mount the panel, fit all four tabs correctly into the grooves on the main body.



#### Conformance to EN/IEC Standards

- When conforming to EMC standards, refer to the information provided in this datasheet for cable selection and other conditions.
- This is a class A product. In residential areas it may cause radio interference, in which case the user may be required to take adequate measures to reduce interference.
- H7CX-A
   —-N: Basic insulation is provided between power supply
   and input terminals, between power supply and output terminals,
   and between input and output terminals. (However, no insulation is
   provided between the power supply and input terminals for the
   H7CX-A
   —D-N.)
- H7CX-R
  -N: Basic insulation is provided between power supply and input terminals and between input and output terminals.
- When double insulation or reinforced insulation is required, apply double insulation or reinforced insulation as defined in IEC 60664 that is suitable for the maximum operating voltage with clearances or solid insulation.
- Connect the input and output terminals to devices that do not have any exposed charged parts.



- Offer: Acceptance. These terms and conditions (these "Terms") are deemed <u>Officer: Acceptance.</u> These terms and conditions (these "<u>Ierms</u>") are deemed part of all quotes, agreements, purchase orders, acknowledgments, price lists, catalogs, manuals, brochures and other documents, whether electronic or in writing, relating to the sale of products or services (collectively, the "<u>Products</u>") by Omron Electronics LLC and its subsidiary companies ("<u>Omron</u>"). Omron objects to any terms or conditions proposed in Buyer's purchase order or other documents which are inconsistent with, or in addition to, these Terms.
- Prices: Payment Terms. All prices stated are current, subject to change without notice by Omron. Omron reserves the right to increase or decrease prices on any unshipped portions of outstanding orders. Payments for Products are
- due net 30 days unless otherwise stated in the invoice.

  <u>Discounts.</u> Cash discounts, if any, will apply only on the net amount of invoices sent to Buyer after deducting transportation charges, taxes and duties, and will be allowed only if (i) the invoice is paid according to Omron's payment terms and (ii) Buyer has no past due amounts.
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- Taxes. All taxes, duties and other governmental charges (other than general real property and income taxes), including any interest or penalties thereon, imposed directly or indirectly on Omron or required to be collected directly or indirectly by Omron for the manufacture, production, sale, delivery, importation, consumption or use of the Products sold hereunder (including customs duties and sales, excise, use, turnover and license taxes) shall be charged to and remitted by Buyer to Omron.

  Financial. If the financial position of Buyer at any time becomes unsatisfactory
- to Omron, Omron reserves the right to stop shipments or require satisfactory security or payment in advance. If Buyer fails to make payment or otherwise comply with these Terms or any related agreement, Omron may (without liability and in addition to other remedies) cancel any unshipped portion of Prod-ucts sold hereunder and stop any Products in transit until Buyer pays all amounts, including amounts payable hereunder, whether or not then due, which are owing to it by Buyer. Buyer shall in any event remain liable for all unpaid accounts.
- Cancellation: Etc. Orders are not subject to rescheduling or cancellation unless Buyer indemnifies Omron against all related costs or expenses.
   Force Majeure. Omron shall not be liable for any delay or failure in delivery
- resulting from causes beyond its control, including earthquakes, fires, floods, strikes or other labor disputes, shortage of labor or materials, accidents to machinery, acts of sabotage, riots, delay in or lack of transportation or the requirements of any government authority.

  11. Shipping: Delivery, Unless otherwise expressly agreed in writing by Omron:
- - a. Shipments shall be by a carrier selected by Omron; Omron will not drop ship except in "break down" situations.
  - b. Such carrier shall act as the agent of Buyer and delivery to such carrier shall constitute delivery to Buyer; c. All sales and shipments of Products shall be FOB shipping point (unless oth-
  - pass from Omron to Buyer; provided that Omron shall retain a security interest in the Products until the full purchase price is paid;

  - d. Delivery and shipping dates are estimates only; and e. Omron will package Products as it deems proper for protection against nor-
- e. Omron will package Products as it deems proper for protection against normal handling and extra charges apply to special conditions.

  12. Claims. Any claim by Buyer against Omron for shortage or damage to the Products occurring before delivery to the carrier must be presented in the Products occurring the presented in the products of shipment and include the original transportation bill signed by the carrier noting that the carrier received the Products the products the products of the product of the p from Omron in the condition claimed.
- Warranties. (a) Exclusive Warranty. Omron's exclusive warranty is that the Products will be free from defects in materials and workmanship for a period of twelve months from the date of sale by Omron (or such other period expressed in writing by Omron). Omron disclaims all other warranties, express or implied. (b) <u>Limitations</u>. OMRON MAKES NO WARRANTY OR REPRESENTATION, EXPRESS OR IMPLIED, ABOUT NON-INFRINGEMENT, MERCHANTABIL-

- ITY OR FITNESS FOR A PARTICULAR PURPOSE OF THE PRODUCTS. BUYER ACKNOWLEDGES THAT IT ALONE HAS DETERMINED THAT THE PRODUCTS WILL SUITABLY MEET THE REQUIREMENTS OF THEIR INTENDED USE. Omron further disclaims all warranties and responsibility of any type for claims or expenses based on infringement by the Products or othany type for claims of expenses based on infringement by the Products of otherwise of any intellectual property right. (c) <u>Buyer Remedy</u>. Omron's sole obligation hereunder shall be, at Omron's election, to (i) replace (in the form originally shipped with Buyer responsible for labor charges for removal or replacement thereof) the non-complying Product, (ii) repair the non-complying Product, or (iii) repay or credit Buyer an amount equal to the purchase price of the non-complying Product; provided that in no event shall Omron be responsible for warranty, repair, indemnity or any other claims or expenses regarding. the Products unless Omron's analysis confirms that the Products were prop erly handled, stored, installed and maintained and not subject to contamina-tion, abuse, misuse or inappropriate modification. Return of any Products by Buyer must be approved in writing by Omron before shipment. Omron Companies shall not be liable for the suitability or unsuitability or the results from the use of Products in combination with any electrical or electronic components, circuits, system assemblies or any other materials or substances or environ-ments. Any advice, recommendations or information given orally or in writing, are not to be construed as an amendment or addition to the above warranty. See OMRON website or contact your Omron representative for pub-lished information.
- Information.

  Limitation on Liability: Etc. OMRON COMPANIES SHALL NOT BE LIABLE FOR SPECIAL, INDIRECT, INCIDENTAL, OR CONSEQUENTIAL DAMAGES, LOSS OF PROFITS OR PRODUCTION OR COMMERCIAL LOSS IN ANY WAY CONNECTED WITH THE PRODUCTS, WHETHER SUCH CLAIM IS BASED IN CONTRACT, WARRANTY, NEGLIGENCE OR STRICT LIABILITY. Further, in no event shall liability of Omron Companies exceed the individual price of the Product on which liability is asserted.
- Indemnities. Buyer shall indemnify and hold harmless Omron Companies and their employees from and against all liabilities, losses, claims, costs and expenses (including attorney's fees and expenses) related to any claim, invesexpenses (including automy's fees and expenses) related to any claim, investigation, litigation or proceeding (whether or not Omron is a party) which arises or is alleged to arise from Buyer's acts or omissions under these Terms or in any way with respect to the Products. Without limiting the foregoing, Buyer (at its own expense) shall indemnify and hold harmless Omron and defend or settle any action brought against such Companies to the extent based on a claim that any Product made to Buyer specifications infringed intellectual property
- rights of another party.

  Property: Confidentiality. Any intellectual property in the Products is the exclusive property of Omron Companies and Buyer shall not attempt to duplicate it in any way without the written permission of Omron. Notwithstanding any charges to Buyer for engineering or tooling, all engineering and tooling shall remain the exclusive property of Omron. All information and materials supplied by Omron to Buyer relating to the Products are confidential and proprietary. and Buyer shall limit distribution thereof to its trusted employees and strictly
- prevent disclosure to any third party.

  <u>Export Controls.</u> Buyer shall comply with all applicable laws, regulations and icenses regarding (i) export of products or information; (iii) sale of products to "forbidden" or other proscribed persons; and (ii) disclosure to non-citizens of regulated technology or information.

  Miscellaneous. (a) Waiver. No failure or delay by Omron in exercising any right and no course of dealing between Buyer and Omron shall operate as a waiver
- of rights by Omron. (b) <u>Assignment</u>. Buyer may not assign its rights hereunder without Omron's written consent. (c) <u>Law</u>. These Terms are governed by the law of the jurisdiction of the home office of the Omron company from which Buyer is purchasing the Products (without regard to conflict of law principles). (d) <u>Amendment</u>. These Terms constitute the entire agreement between Buyer and Omron relating to the Products, and no provision may be changed or waived unless in writing signed by the parties. (e) <u>Severability</u>. If any provision hereof is rendered ineffective or invalid, such provision shall not invalidate any other provision. (f) <u>Setoff</u>. Buyer shall have no right to set off any amounts against the amount owing in respect of this invoice. (g) <u>Definitions</u>. As used herein, "<u>including</u>" means "including without limitation"; and "<u>Omron Companies</u>" (or similar words) mean Omron Corporation and any direct or indirect subsidiary or affiliate thereof.

# Certain Precautions on Specifications and Use

- Suitability of Use. Omron Companies shall not be responsible for conformity with any standards, codes or regulations which apply to the combination of the Product in the Buyer's application or use of the Product. At Buyer's request, Omron will provide applicable third party certification documents identifying ratings and limitations of use which apply to the Product. This information by itself is not sufficient for a complete determination of the suitability of the Product. uct in combination with the end product, machine, system, or other application or use. Buyer shall be solely responsible for determining appropriateness of the particular Product with respect to Buyer's application, product or system. Buyer shall take application responsibility in all cases but the following is a non-exhaustive list of applications for which particular attention must be given:

  (i) Outdoor use, uses involving potential chemical contamination or electrical interference, or conditions or uses not described in this document.

  (ii) Use in consumer products or any use in significant quantities.

  - (iii) Energy control systems, combustion systems, railroad systems, aviation systems, medical equipment, amusement machines, vehicles, safety equipment, and installations subject to separate industry or government regulations. (iv) Systems, machines and equipment that could present a risk to life or property. Please know and observe all prohibitions of use applicable to this Prod-
  - NEVER USE THE PRODUCT FOR AN APPLICATION INVOLVING SERIOUS RISK TO LIFE OR PROPERTY OR IN LARGE QUANTITIES WITHOUT ENSURING THAT THE SYSTEM AS A WHOLE HAS BEEN DESIGNED TO

- ADDRESS THE RISKS, AND THAT THE OMRON'S PRODUCT IS PROP-ERLY RATED AND INSTALLED FOR THE INTENDED USE WITHIN THE OVERALL EQUIPMENT OR SYSTEM.
- Programmable Products. Omron Companies shall not be responsible for the
- user's programming of a programmable Product, or any consequence thereof.

  Performance Data. Data presented in Omron Company websites, catalogs and other materials is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of Omron's test conditions, and the user must correlate it to actual application requirements. Actual performance is subject to the Omron's Warranty and Limitations of Liability
- Change in Specifications. Product specifications and accessories may be changed at any time based on improvements and other reasons. It is our practice to change part numbers when published ratings or features are changed, or when significant construction changes are made. However, some specifica-tions of the Product may be changed without any notice. When in doubt, spe-cial part numbers may be assigned to fix or establish key specifications for your application. Please consult with your Omron's representative at any time to confirm actual specifications of purchased Product.
- Errors and Omissions. Information presented by Omron Companies has been checked and is believed to be accurate; however, no responsibility is assumed for clerical, typographical or proofreading errors or omissions.